
developer.skatelescope.org

Documentation

SKA Organization

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OVERVIEW

The Mid.CBF Master Control Software (MCS) provides a high-level interface to the Telescope Monitoring and Control (TMC) and CSP_Mid Local Monitoring and Control (LMC), and translates the high-level commands into the configuration and control of individual Talon-DX boards.

1.1 System Context

The following diagram shows MCS as it fits into the rest of the CSP Mid system.

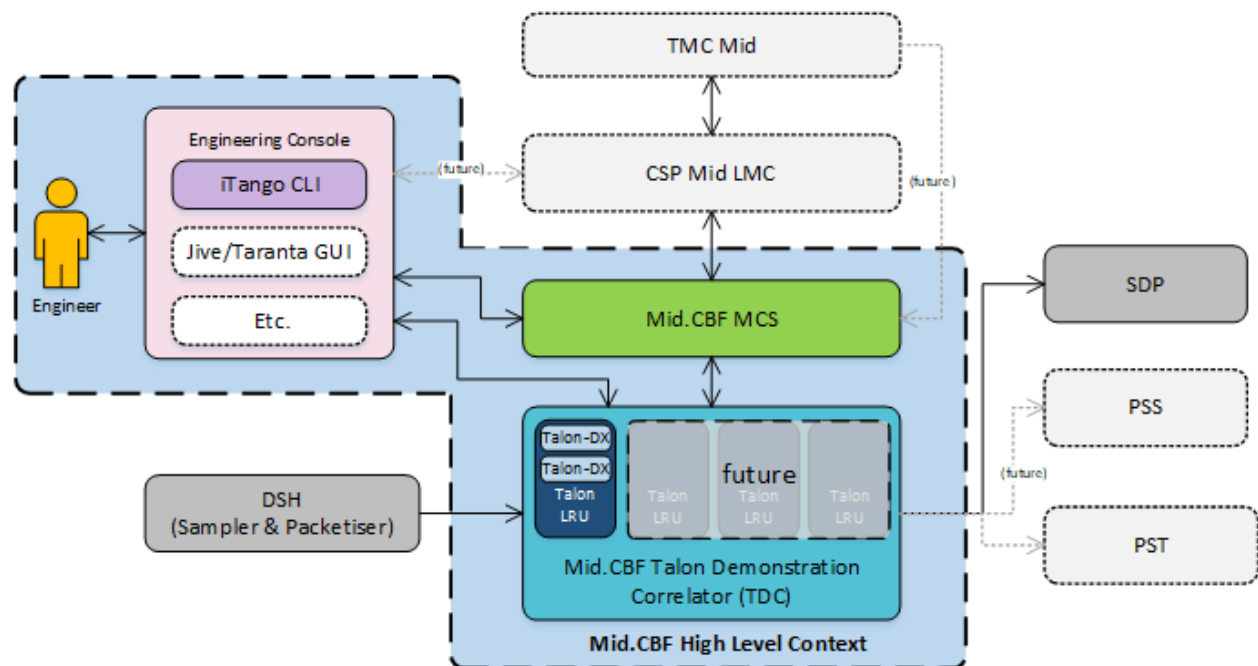


Fig. 1: MCS System Context

MCS interacts with TMC and CSP_Mid LMC and controls the applications and low-level device servers that run on the hard processor system (HPS) of the Talon-DX boards. The diagram below shows these interactions. TMC and CSP_Mid LMC interact with the CBF Controller and CBF Subarray. The diagram also shows the Engineering Console and pytest-BDD elements which are used to test the interfaces between MCS and TMC/CSP_Mid LMC during development.

In MCS there is one VCC device and one FSP device for each VCC/FSP in the system. These devices communicate directly with the top level HPS application for the reconfiguration of the Talon-DX functionality (VCC Controller / HPS FSP Controller)

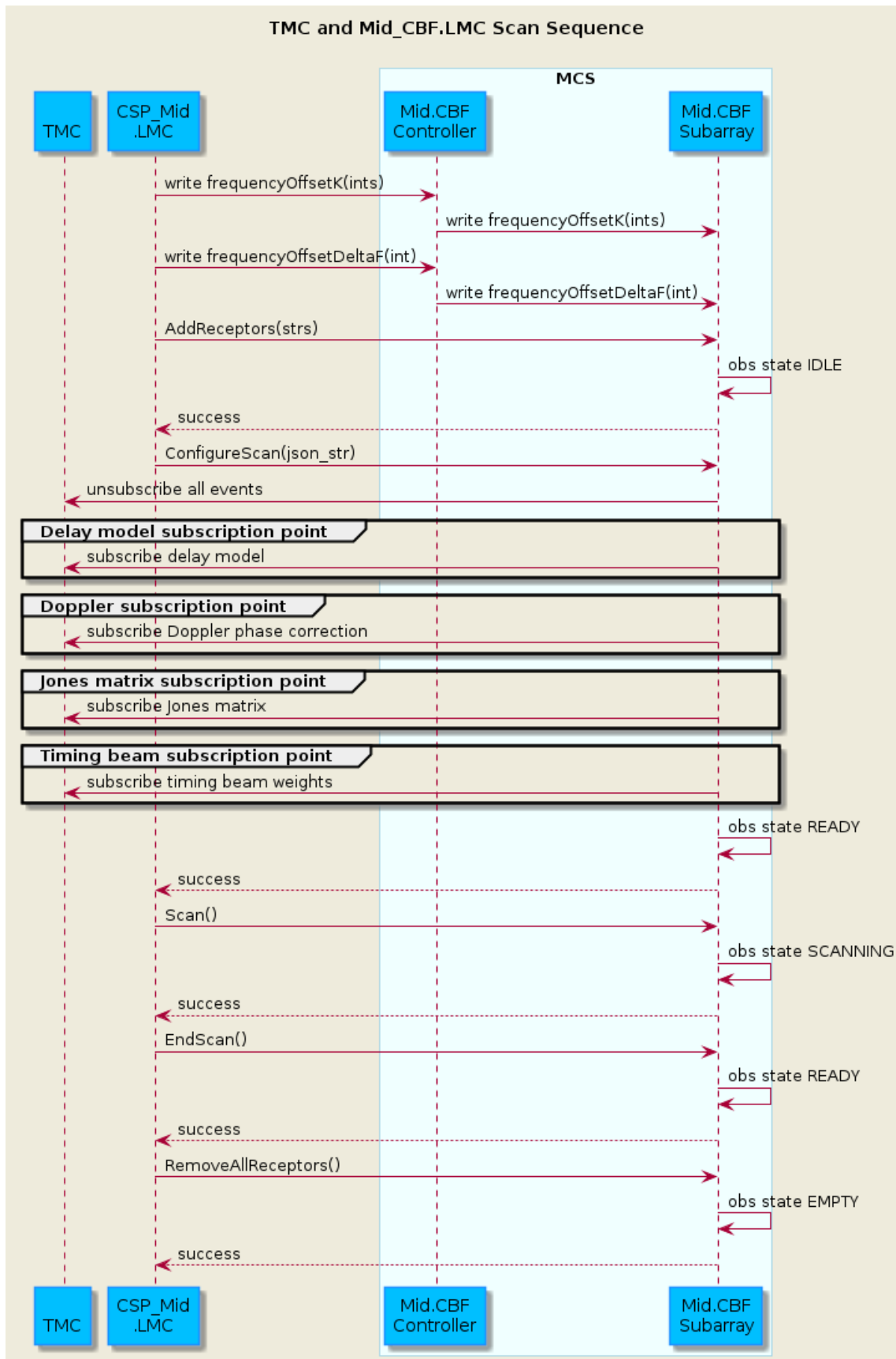
LMC TO MCS

MCS provides commands and attributes to turn MCS on and off (through the CBF Controller) as well as commands needed to configure and execute scans through the subarrays. (CBF Subarray)

The sequence diagram below shows the interactions between LMC and MCS to assign receptors to a subarray, configure a scan, and run a scan. It shows configuration of one Mid.CBF subarray followed by running a scan on that subarray. It ends with no receptors assigned to the subarray. The calls to write the frequency offset K and frequency offset delta F values only need to be written when there are updates to the values. They must be written to the CBF Controller before the scan configuration.

For full details of MCS Controller see [*CbfController*](#).

For full details of MCS Subarray see [*CbfSubarray*](#).



2.1 CbfController Tango Commands

Command	Parameters	Return type	Action
Off	None	(ResultCode, str)	Turn off the controller and subordinate devices
Standby	None	(ResultCode, str)	Put in low power mode
On	None	(ResultCode, str)	Turn on the controller and subordinate devices

2.2 CbfSubarray Tango Commands

Command	Parameters	Return type	Action
Abort	None	(ResultCode, str)	Abort subarray configuration or operation
AddReceptors	List[str]	(ResultCode, str)	Assign receptors to this subarray Turn subarray to ObsState = IDLE if no receptor was previously assigned
ConfigureScan	JSON str*	(ResultCode, str)	Change state to configuring Configure attributes from input JSON Subscribe events Configure VCC, VCC subarray, FSP, FSP Subarray. Publish output links.
EndScan	None	(ResultCode, str)	End the scan
ObsReset	None	(ResultCode, str)	Reset subarray scan configuration
Off	None	(ResultCode, str)	Set subarray power mode to off. Commands FSP<function mode> Subarrays to turn off
On	None	(ResultCode, str)	Set subarray power mode to on. Commands FSP<function mode> Subarrays to turn on
RemoveAllReceptors	None	(ResultCode, str)	Remove all receptors Turns Subarray off if no receptors are assigned
RemoveReceptors	List[str]	(ResultCode, str)	Remove receptors in input list
2.2. CbfSubarray Tango Commands			Turns Subarray to ObsState=EMPTY if no receptors assigned

- Schema for JSON string defined in the [Telescope Model - Mid.CBF](#) schemas

MCS TO HPS

The interface from the MCS to the HPS is largely in the form of communication between Tango devices running on either side.

The interface also currently consists of low-level SSH calls from the MCS to the Talon-DX boards, which are used to copy FPGA bitstreams and Tango device server binaries to the boards and start the HPS Master process. This functionality may be moved in the future, but for now it is implemented in the *TalonDxComponentManager Class*, which is instantiated by the *CbfController*.

3.1 MCS and HPS Master DS

The interface between the MCS and the HPS Master device server is primarily made up of the `configure` command sent from the MCS to the HPS master, which programs the FPGA and spawns the remaining HPS device servers. Before this command can be run, it is expected that the MCS has already copied the necessary bitstreams and binaries to the board and the HPS master has obviously been started. This is all handled automatically as part of the *MCS On Command*.

The `configure` command has one argument, which is a JSON-formatted string. An example of its contents can be seen below.

```
{
  "description": "Configures Talon DX to run VCC firmware and devices.",
  "target": "talon1",
  "ip_address": "169.254.100.1",
  "ds_hps_master_fqdn": "talondx-001/hpsmaster/hps-1",
  "fpga_path": "/lib/firmware",
  "fpga_dtb_name": "vcc3_2ch4.dtb",
  "fpga_rbf_name": "vcc3_2ch4.core.rbf",
  "fpga_label": "base",
  "ds_path": "/lib/firmware/hps_software/vcc_test",
  "server_instance": "talon1_test",
  "devices": [
    "dscircuitswitch",
    "dsdct",
    "dsfinechannelizer",
    "dstalondxrdma",
    "dsvcc"
  ]
}
```

3.2 MCS On Command

The following diagram shows the CbfController On command sequence and how it integrates with other components in the Mid.CBF system. The steps are outlined in detail in the [Engineering Console](#).

From a MCS perspective, the On command sequence consists of the following steps:

- Arrows 4-7: Power on the Talon-DX boards
- Arrow 9: Attempt to connect to each board over SSH (see *TalonDxComponentManager Class*)
- Arrows 8-9: Copy the relevant binaries and bitstreams to each board
- Arrow 10: Start up the HPS Master on each board
- Arrow 12: Send the configure to each HPS Master device server

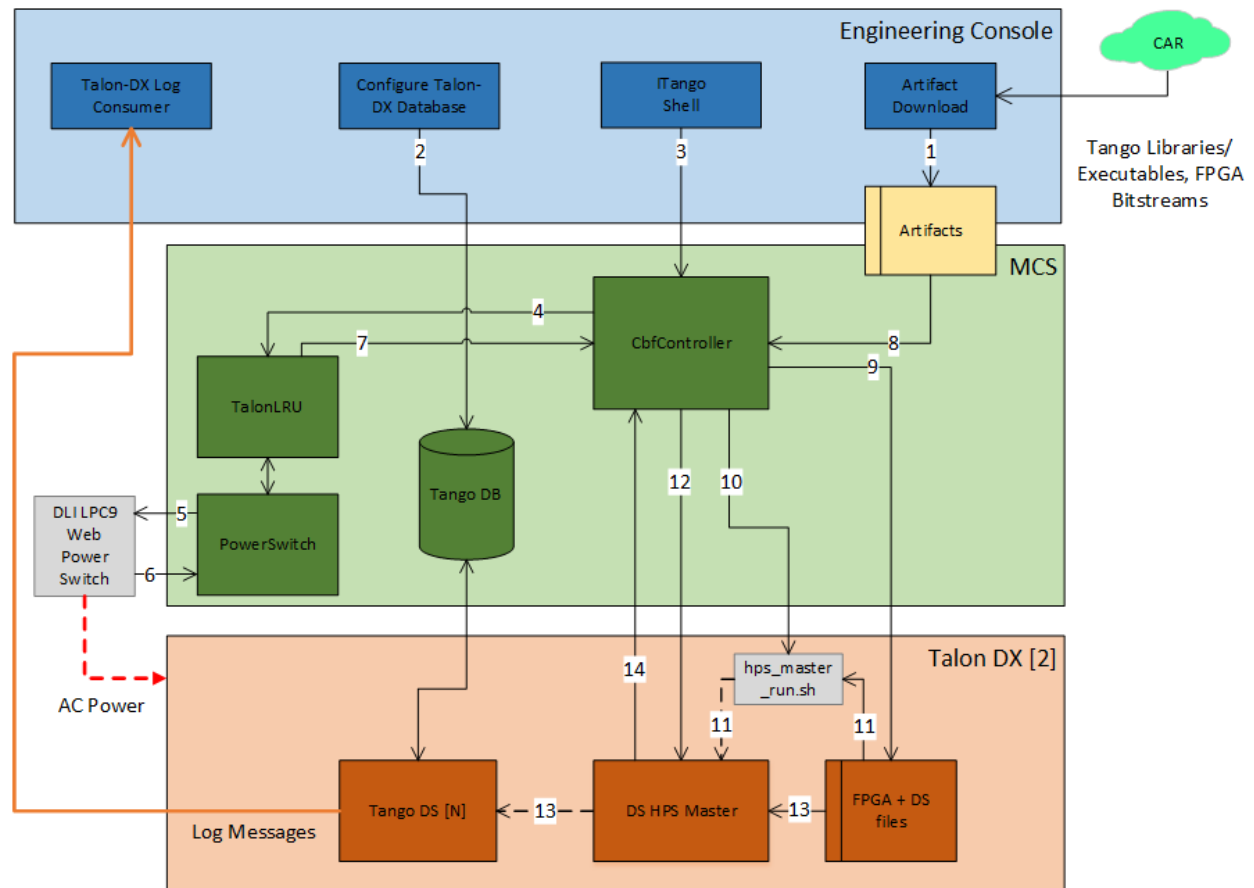
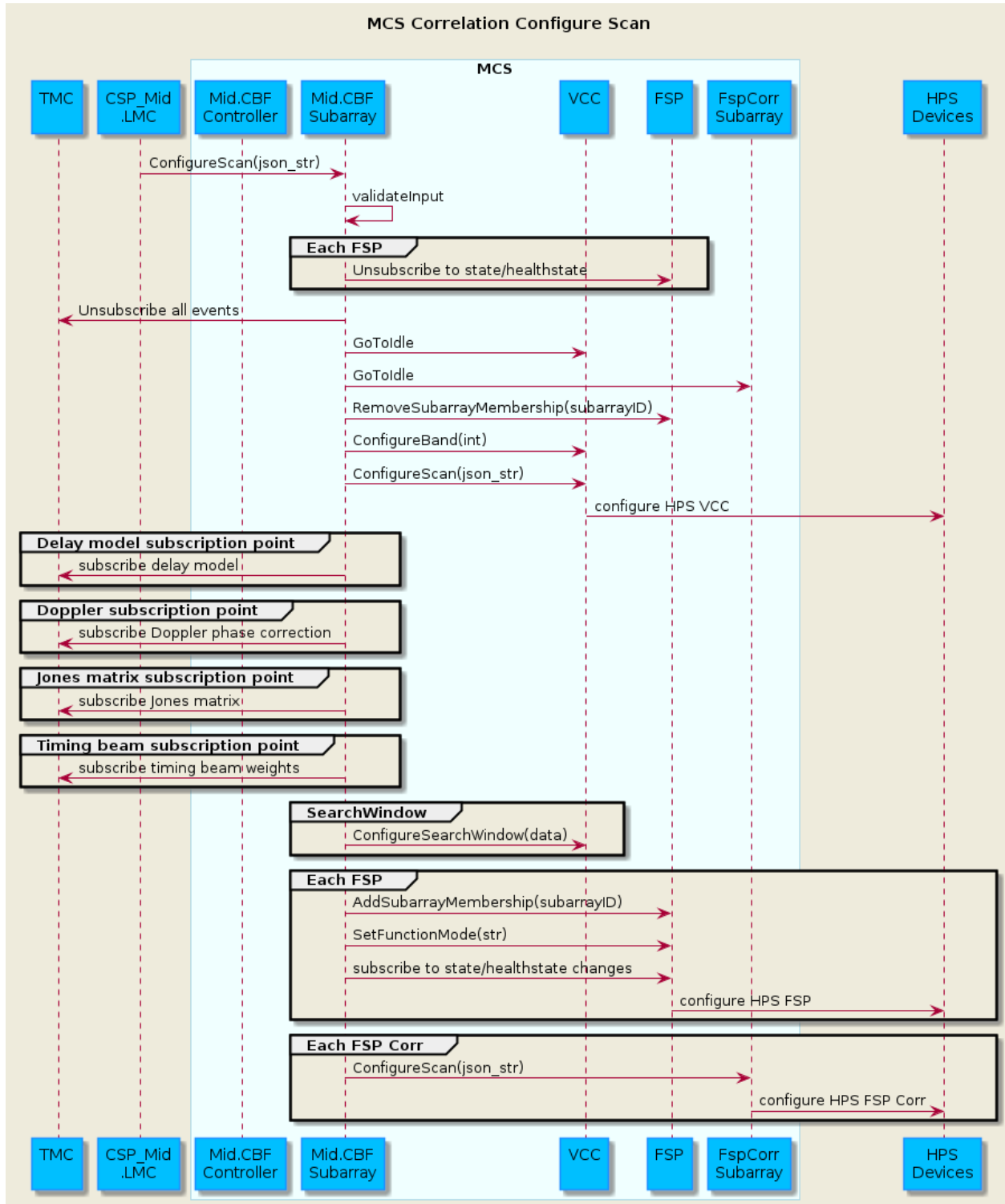


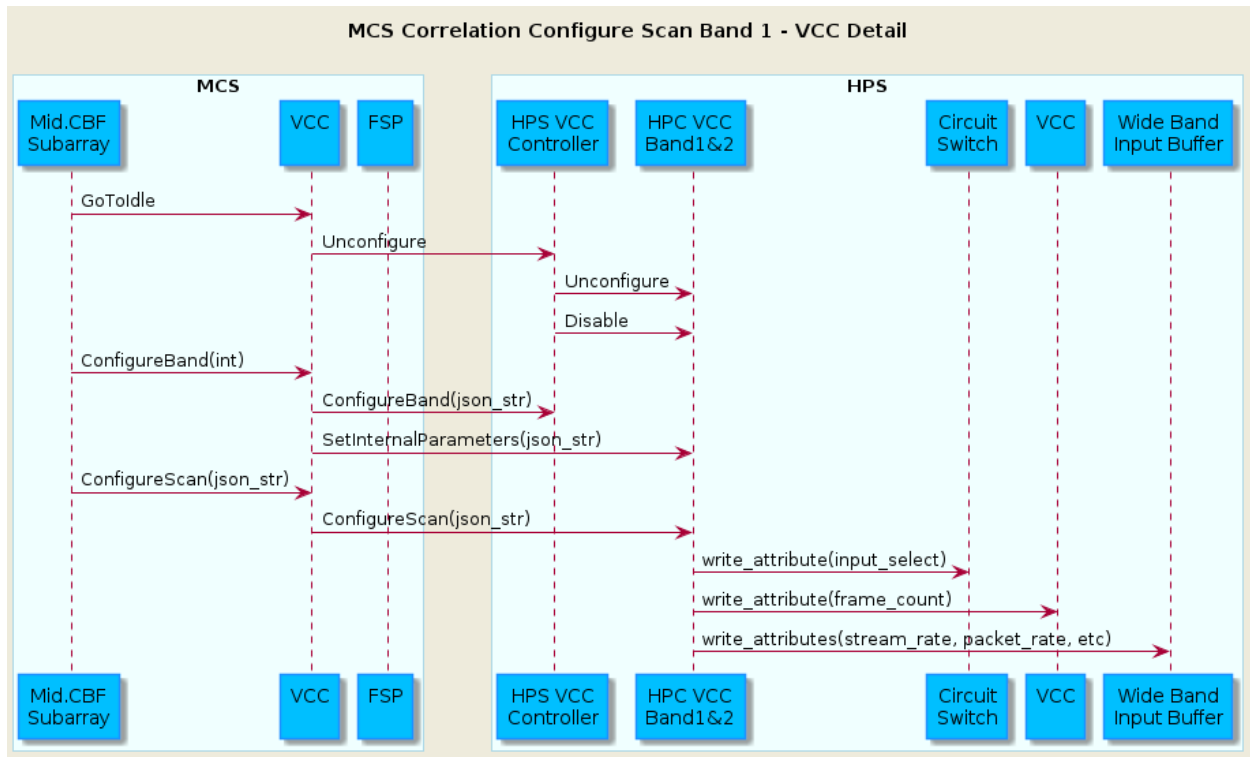
Fig. 1: MCS On Command Sequence

3.3 Configure Scan Command Sequence

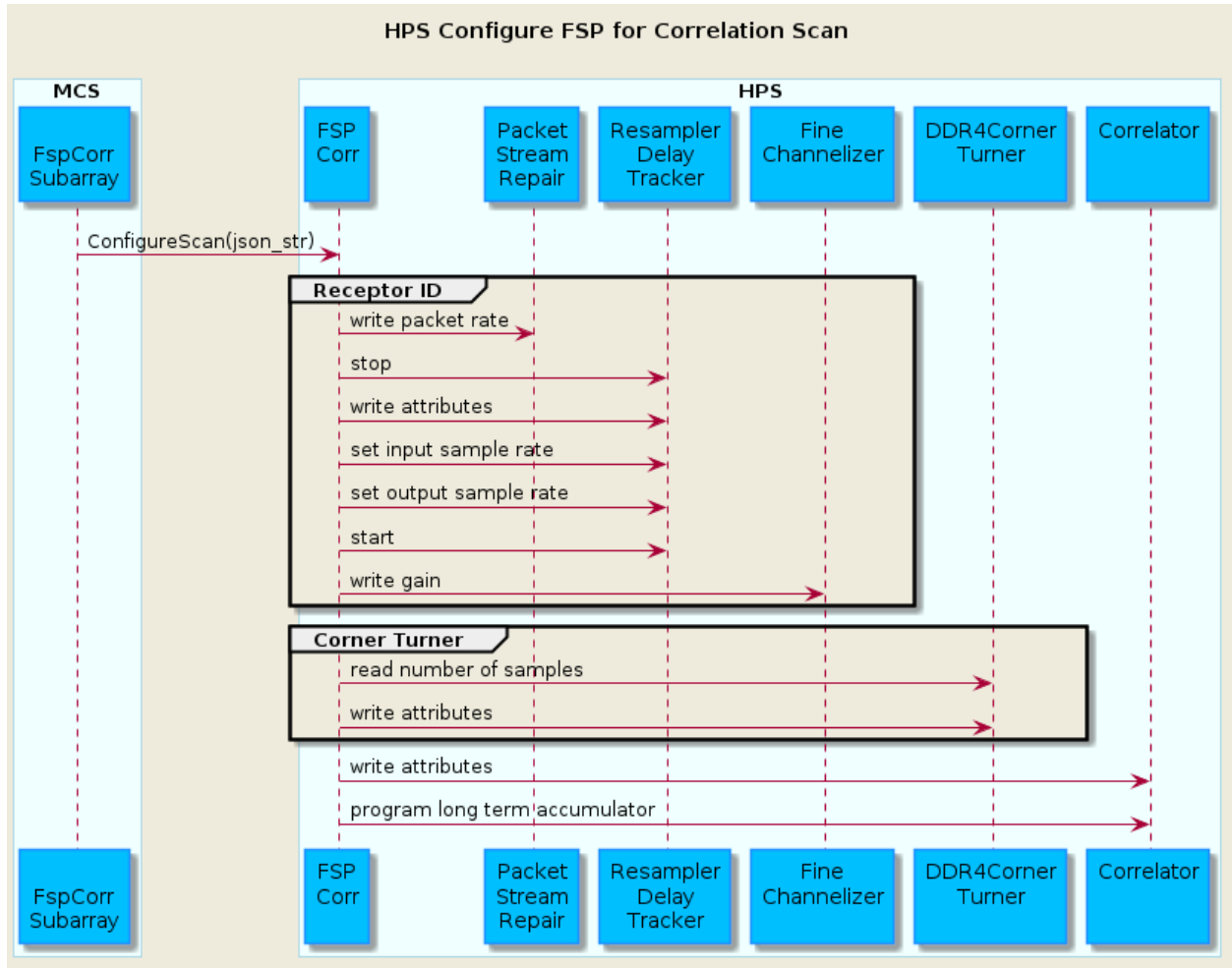
The sequence diagram below shows the main sequence of calls in MCS to configure a correlation scan. Return calls are not shown.



The sequence diagram below shows additional detail for configuration of the VCC for a correlation scan.



The sequence diagram below shows details of calls to configure a FSP for a correlation scan.



GETTING STARTED

4.1 Developer Setup

This section follows the instructions on the SKA developer's portal:

- Dev Environment Setup
- Dev FAQs

4.2 Git Repository

The MCS Git Repository is available at the following page: <https://gitlab.com/ska-telescope/ska-mid-cbf-mcs>

The README on the repository will guide users through cloning and initializing the repository.

4.3 Running the Mid CBF MCS

The ska-mid-cbf-mcs Tango device servers are started and run via Kubernetes.

Make sure Kubernetes/minikube and Helm have been installed (and verified) as described in the 'Set up Kubernetes' section.

Note: You may need to change permission to the .minikube and .kube files in your home directory:

```
sudo chown -R <user_name>:<user_name> ~/.minikube/  
sudo chown -R <user_name>:<user_name> ~/.kube/
```

4.3.1 1. Make sure minikube is up and running

The following commands use the default minikube profile. If you are running the MCS on the Dell server you will need to set up your own minikube profile. A new minikube profile is needed for a new cluster, so creating minikube profiles ensures two users on the Dell server do not work on the same cluster at the same time. To view the modifications needed to run the following commands on a new minikube profile see Minikube Profiles

```
minikube start    # start minikube (local kubernetes node)  
minikube status  # check current status of minikube
```

The minikube status output should be:

```
minikube
type: Control Plane
host: Running
kubelet: Running
apiserver: Running
kubeconfig: Configured
```

If restarting a stopped minikube; from local ska-cicd-deploy-minikube repository run `make minikube-metallb-config` to reapply metallb configMap to determine pod LoadBalancer service external IP addresses.

4.3.2 2. From the root of the project, build the application image.

```
cd ska-mid-cbf-mcs
eval $(minikube docker-env)    # to use the minikube's docker environment
make oci-image-build          # if building from local source and not artefact repository
```

`make oci-image-build` is required only if a local image needs to be built, for example every time the SW has been updated. For development, in order to get local changes to build, run `eval $(minikube docker-env)` before `make build`

Note: To check if you are within the minikube's docker environment, use the `minikube status` command. It will indicate `docker-env: in use` if in use as follows:

```
minikube
type: Control Plane
host: Running
kubelet: Running
apiserver: Running
kubeconfig: Configured
docker-env: in-use
```

4.3.3 3. Install the umbrella chart.

```
make k8s-install-chart        # deploy from Helm charts
make k8s-install-chart-only   # deploy from Helm charts without updating dependencies
```

Note: `make k8s-watch` will list all of the pods' status in every 2 seconds using `kubectl`; `make k8s-wait` will wait until all jobs are 'Completed' and pods are 'Running'.

4.3.4 4. (Optional) Create python virtual environment to isolate project specific dependencies from your host environment.

```
virtualenv venv                # create python virtualenv 'venv'
source venv/bin/activate        # activate venv
```

4.3.5 5. Install linting and testing requirements.

```
make requirements
```

4.3.6 6. Install the MCS package in editable mode.

```
pip install -e .
```

4.3.7 7. Run a test.

```
make k8s-test # functional tests with an already running deployment
make python-test # unit tests, deployment does not need to be running
```

Note: add `-k pytest` flags in `setup.cfg` in the project root to limit which tests are run

4.3.8 8. Tear down the deployment.

```
make k8s-uninstall-chart # uninstall deployment from Helm charts
deactivate # if in active virtualenv
eval $(minikube docker-env --unset) # if docker-env variables were set previously
minikube stop # stop minikube
```

4.4 Useful Minikube Commands

4.4.1 Create a minikube

```
minikube start
```

4.4.2 Check the status of the cluster created for your minikube

```
minikube status
```

4.4.3 Fixing a Misconfigured Kubeconfig

If the kubeconfig is pointing to a stale minikube and is showing as **Misconfigured** when checking the minikube status, or if the minikube's IP or port has changed, update the context as follows:

```
minikube update-context
```

4.4.4 Delete a minikube profile

```
minikube delete
```

4.4.5 Set and unset docker-env variables

```
eval $(minikube docker-env)
eval $(minikube docker-env --unset)
```

4.5 Taranta

This provides a graphical user interface using Taranta (previously known as WebJive); to set it up:

- Add the following line to `/etc/hosts`:

```
192.168.49.2 taranta
```

Note: 192.168.49.2 is the minikube IP address, obtainable with the command `minikube ip`

- Navigate to `taranta/ska-mid-cbf/taranta/devices` in a browser (works best with Google Chrome).

The following credentials can be used to operate the system:

- Username: `user1`
- Password: `abc123`

The device tree can be viewed and explored. In addition, device attributes can be seen and modified, and device commands can be sent, by creating and saving a new dashboard.

4.6 Generating Documentation

To re-generate the documentation locally prior to checking in updates to Git:

```
make docs-build html
```

To see the generated documentation, open `/ska-mid-cbf-mcs/docs/build/html/index.html` in a browser – e.g.,

```
firefox docs/build/html/index.html &
```

4.7 Releasing

For a new release (i.e. prior to merging a branch into main) update the following files by incrementing version/release/tag number fields to conform to the semantic versioning convention:

- `.release`: `release=` and `tag=`
- `src/ska_mid_cbf_mcs/release.py`: `version =`
- `charts/ska-mid-cbf/Chart.yaml`: `version:` and `appVersion:`
- `charts/ska-mid-cbf/values.yaml`: `midcbf:image:tag:`

- charts/ska-mid-cbf-tmleafnode/Chart.yaml: version: and appVersion:
- charts/ska-mid-cbf-tmleafnode/values.yaml: midcbf:image:tag:
- charts/mid-cbf-umbrella/Chart.yaml:
 - version: and appVersion:
 - version: under ska-mid-cbf and ska-mid-cbf-tmleafnode

Note: appVersion represents the version of the application running, so it corresponds to the ska-mid-cbf-mcs docker image version.

Once a new release has been merged into main, create a new tag on GitLab and run the manual “publish-chart” stage of the tag pipeline to publish the Helm charts.

4.8 Development resources

4.8.1 Other resources

See more tango device guidelines and examples in the `ska-tango-examples` repository

4.8.2 Useful commands

Kubernetes

For Kubernetes basic kubectl commands see: <https://kubernetes.io/docs/reference/kubectl/cheatsheet/>

To display components of the MCS Kubernetes system:

```
kubectl get all -n ska-mid-cbf
kubectl describe <component-name> -n ska-mid-cbf # info on a particular component
```

This should list the following running pods:

- `cbfcontroller-controller-0` : The CbfController TANGO device server.
- `cbfsubarrayxx-cbf-subarray-xx-0`: `xx` ranges from `01` to `03`. The 3 instances of the CbfSubarray TANGO device server.
- `fspxx-fsp-xx-0`: `xx` ranges from `01` to `04`. The 4 instances of the FspMulti TANGO device servers.
- `vccxxx-vcc-xxx-0`: `xxx` ranges from `001` to `004`. The 4 instances of the VccMulti TANGO device servers.
- `tmcspsubarrayleafnodetestx-tmx-0`: `x` ranges from `1` to `2`. The 2 instances of the TmCspSubarrayLeafNodeTest TANGO device servers.
- `tango-host-databases-from-makefile-test-0`: The TANGO DB device server.
- etc.

4.9 License

See the LICENSE file for details.

CODE ELEMENT DESIGN NOTES

5.1 Component Managers

More details about the role of component managers can be found in the [SKA Tango Base Documentation](#). In the Mid.CBF MCS each component has a Tango device class and a component manager class. The Tango device class updates its state model(s) (the `op_state_model` and/or `obs_state_model`). The Tango device class does not directly communicate with its component, instead it tells its component manager class what to do by calling its methods. The component manager class directly interacts with its component. Its role is to establish communication with its component and monitor and control it. An example of this Tango device and component manager interaction is shown in the diagram below.

5.2 Cbf Controller

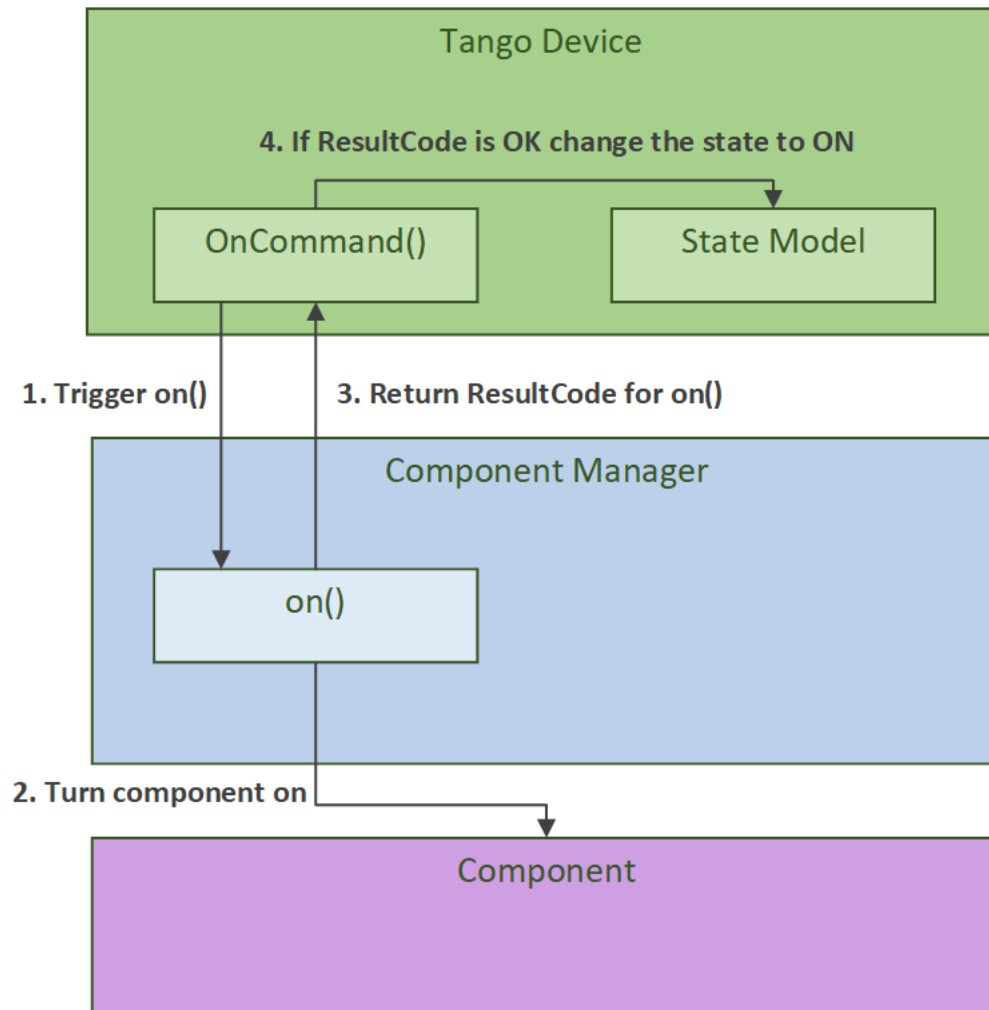
The `CbfController` Tango device controls its subordinate Tango devices: `Fsp`, `Vcc`, `CbfSubarray` and `TalonLRU`. It is responsible for turning these subordinate devices on and off, and putting the `Fsp`, `Vcc` and `CbfSubarray` devices in STANDBY mode. The `CbfController` also initiates the configuration of the Talon-DX boards. The `CbfController` device's `OnCommand` triggers `TalonDxComponentManager.configure_talons` to be called which copies the device server binaries and FPGA bitstream to the Talon-DX boards, starts the HPS master device server and sends the configure command to each `DsHpsMaster` device.

5.3 Cbf Subarray

The `CbfSubarray` Tango device is used to monitor and control scan operation of a Mid.CBF receptor subarray. This device receives one configuration per scan, and a subarray may accept this scan configuration only after being assigned at least one receptor.

5.3.1 Receptor assignment

Receptor assignment to a subarray is done before configuration for a scan. Receptor assignment is exclusive; receptors assigned to one subarray cannot belong to any other subarray. Up to 197 receptors can be assigned to one subarray; currently, there is only support for 4 receptors.



5.3.2 Scan configuration

Subarrays receive a scan configuration via an ASCII encoded JSON string. The scan configuration is validated for completeness and its parameters implemented as Tango device attributes; the subarray device will then also configure subordinate devices with the relevant parameters, including VCC, FSP and FSP-subarray devices.

5.4 Frequency Slice Processor (FSP)

The Fsp Tango device is used for monitoring and control of a Frequency Slice Processor (FSP) during scan operation. An FSP device can be configured for processing of one of up to twenty-six frequency slices (depending on observational frequency band). Additionally, an FSP can be assigned to any number of subarrays with matching configurations.

5.4.1 Fsp Function Mode

There are four function modes available for FSP scan configuration, each with a corresponding function mode capability and subarray device per FSP; furthermore, each FSP function mode subarray device corresponds to a unique pairing of one FSP with one subarray. Currently, one subarray and four FSPs are supported.

FSP Function Mode Subarray devices:

- Correlation (CORR): FspCorrSubarray
- Pulsar Search Beamforming (PSS-BF): FspPssSubarray
- Pulsar Timing Beamforming (PST-BF): FspPstSubarray
- VLBI Beamforming (VLBI): FspVlbiSubarray

5.5 Mid.Cbf VCC Device Server (VccMulti)

5.5.1 VCC Device

The Vcc Tango device is used to control and monitor the functionality for a single Talon-DX board that runs VCC functionality. This device communicates with the top-level VCC device server running on the Talon-DX board to coordinate setup and processing activities of low-level device servers.

The Vcc device can operate in either simulation mode or not. When in simulation mode (this is the default), simulator classes are used in place of communication with the real Talon-DX Tango devices. This allows testing of the MCS without any connection to the hardware.

5.6 Talon LRU

The TalonLRU Tango device handles the monitor and control functionality for a single Talon LRU. A TalonLRU instance must therefore be created for each LRU. Currently this device only controls the power to the LRU via a proxy to the PowerSwitch device.

The operational state of this device always reflects the power state of the LRU. If at least one of the PDU outlets connected to the LRU is switched on, the state of the TalonLRU device should be ON. If both outlets are switched off, then the state should be OFF.

If the state of the outlets is not consistent with the state of the TalonLRU device when it starts up (or when `simulationMode` of the PowerSwitch device changes), the TalonLRU device transitions into a FAULT state. The

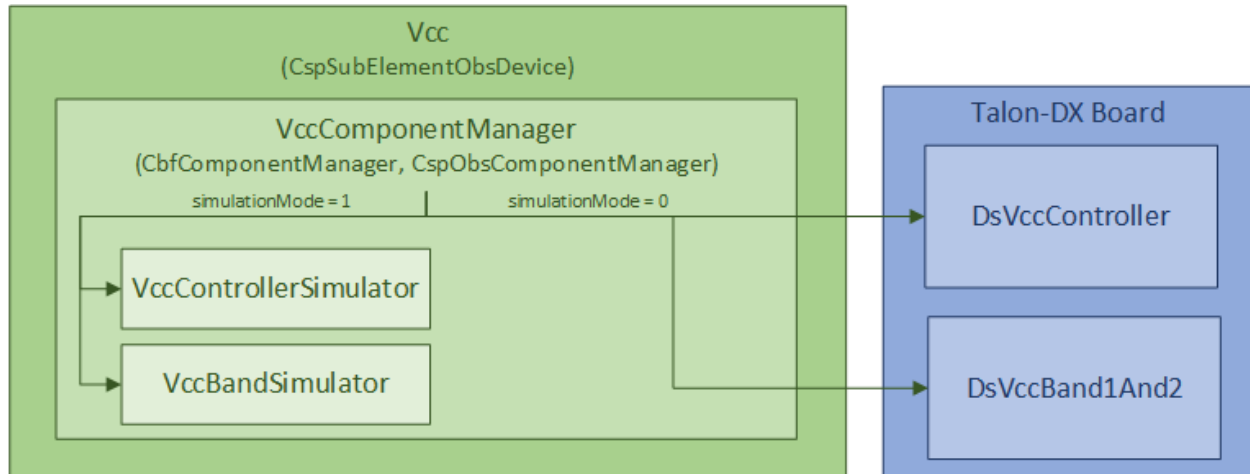


Fig. 1: MCS Vcc Device

power outlets must then be manually switched to the expected startup state via some other method before resetting the TalonLRU device.

The expected startup state of the device is OFF.

5.7 Power Switch

The PowerSwitch Tango device is used to control and monitor the web power switch that provides power to the Talon LRUs. The current power switch in use is the DLI LPC9 ([User Guide](#)). The power switch has 8 programmable outlets, meaning that it can power up to 4 Talon LRUs (each LRU needs two power supply lines).

The PowerSwitch device can be operated in either simulation mode or not. When in simulation mode (this is the default), the PowerSwitchSimulator is used in place of communication with the real power switch hardware. This allows testing of the MCS with no hardware connected.

When integration testing with the hardware is desired, the `simulationMode` attribute can be set to 0. This initializes communication with the real power switch via the PowerSwitchDriver, and queries the list of outlets in the power switch.

Important operational notes:

- Certain requests to the power switch hardware can take longer than others, hence a timeout of 4 seconds set in the PowerSwitchDriver. As such, accessing attributes or commands in the PowerSwitch device can take longer than the default Tango timeout (3 seconds). Any DeviceProxy of the PowerSwitch device should increase its timeout to 5 seconds to safely complete all requests (both successful and unsuccessful) before the Tango timeout. This can be done using `pwr_dev_proxy.set_timeout_millis(5000)`, assuming `pwr_dev_proxy` is a DeviceProxy to the PowerSwitch device.
- Although the DLI LPC9 claims to support up to 8 concurrent clients, testing has shown a significant slow down in response time when more than one request has been sent to the power switch. As such, all communication with the power switch should be kept sequential. Currently the PowerSwitchDriver does not ensure this. If the PowerSwitch device is ever changed to handle requests asynchronously, the PowerSwitchDriver should also be updated to only process one request at a time.

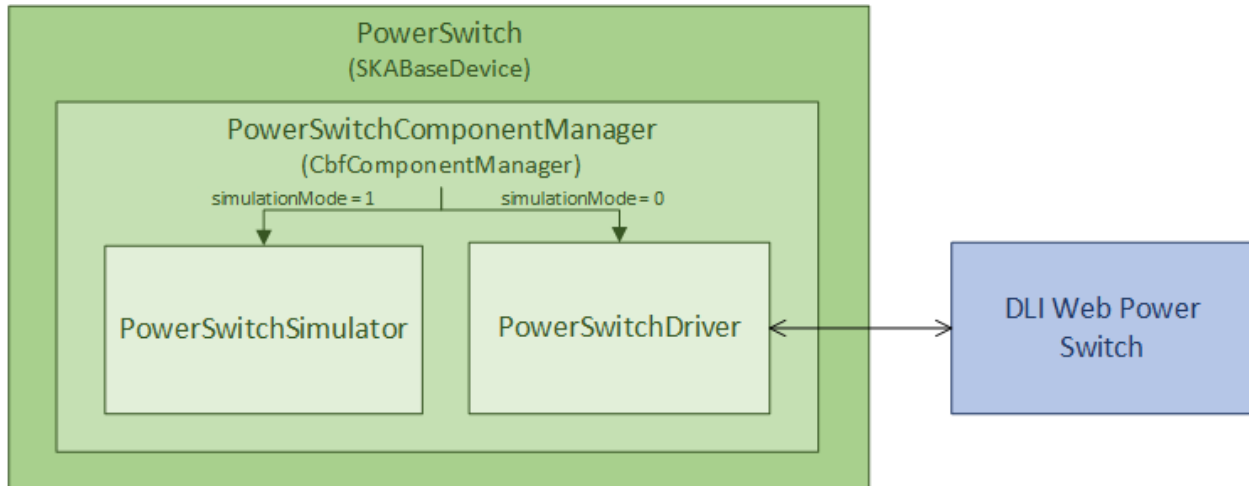


Fig. 2: MCS PowerSwitch Device

5.8 Talon DX Log Consumer

The Talon DX Log Consumer is a Tango device intended to run on the host machine that connects to the Talon-DX boards. This Tango device is set up as a default logging target for all the Tango device servers running on the HPS of each Talon-DX board. When the HPS device servers output logs via the Tango Logging Service, the logs get transmitted to this log consumer device where they get converted to the SKA logging format and outputted once again via the SKA logging framework. In this way logs from the Talon-DX boards can be aggregated in once place and eventually shipped to the Elastic framework in the same way as logs from the Mid CBF Monitor and Control Software (MCS).

Note: more instances of the device may be created to provide enough bandwidth for all the HPS device servers.

5.8.1 Connecting from HPS DS to the Log Consumer

The Talon-DX boards connect to the host machine (currently known as the development server) over a single Ethernet connection. The IP address of the development server on this connection is 169.254.100.88 and all outgoing traffic from the Talon-DX boards must be addressed to this IP.

When the log consumer starts up on the development server, the OmniORB end point (IP address and port) it is assigned is local to the development server (i.e. IP address 142.73.34.173, arbitrary port). Since the Talon boards are unable to connect to this IP address, we need to manually publish a different endpoint when starting up the log consumer that is visible to the HPS devices.

The following ORB arguments are used (see the make target `talondx-log-consumer`):

- `-ORBEndPointPublish giop:tcp:169.254.100.88:60721`: Exposes this IP address and port to all clients of this Tango device. When the HPS device servers contact the database to get the network information of the log consumer, this is the IP address and port that is returned. The IP addresses matches that of the Ethernet connection to the development server, allowing the HPS device servers to direct their messages across that interface.
- `-ORBEndPoint giop:tcp:142.73.34.173:60721`: Assigns the IP address and port that the log consumer device is actually running on. This needs to be manually assigned since an iptables mapping rule was created on the development server to route any TCP traffic coming in on 169.254.100.88:60721 to 142.73.34.173:60721.

Some important notes:

- Due to the end point publishing, no Tango devices running on the development server will be able to connect to the log consumer (including being able to configure the device from Jive). This is because the published IP address is not accessible on the development server. There may be a way to publish multiple endpoints, but this needs further investigation.
- If the log consumer device cannot be started due to an OmniORB exception saying that the end point cannot be created, it is possible that the 142.73.34.173 needs to change to something else. It is not yet clear why this can happen. To change it do the following:
 - Remove the ORB arguments from the `talondx-log-consumer` make target, and then start the log consumer.
 - Open up Jive and look at what IP address is automatically assigned to the log consumer device. This is the IP address that we now need to use for the endpoint.
 - Find the iptables rule that maps 169.254.100.88:60721 to 142.73.34.173:60721, and change it to the new IP address.
 - Add the ORB arguments back in, using the correct IP address for the end point.

6.1 CbfComponentManager

6.1.1 CbfComponentManager Class

```
class ska_mid_cbf_mcs.component.component_manager.CbfComponentManager(*args: Any, **kwargs: Any)
```

Bases: BaseComponentManager

A base component manager for SKA Mid.CBF MCS

This class exists to modify the interface of the `ska_tango_base.base.component_manager.BaseComponentManager`. The `BaseComponentManager` accepts an `op_state_model` argument, and is expected to interact directly with it. This is not a very good design decision. It is better to leave the `op_state_model` behind in the device, and drive it indirectly through callbacks.

Therefore this class accepts three callback arguments: one for when communication with the component changes, one for when the power mode of the component changes, and one for when the component fault status changes. In the last two cases, callback hooks are provided so that the component can indicate the change to this component manager.

start_communicating() → None

Start communicating with the component.

stop_communicating() → None

Break off communicating with the component.

update_communication_status(communication_status: CommunicationStatus) → None

Handle a change in communication status.

This is a helper method for use by subclasses.

Parameters

communication_status – the new communication status of the component manager.

property is_communicating: bool

Return communication with the component is established.

SKA Mid.CBF MCS uses the more expressive `communication_status` for this, but this is still needed as a base classes hook.

Returns

whether communication with the component is established.

property communication_status: `CommunicationStatus`

Return the communication status of this component manager.

This is implemented as a replacement for the `is_communicating` property, which should be deprecated.

Returns

status of the communication channel with the component.

update_component_power_mode(*power_mode*: `Optional[ska_tango_base.control_model.PowerMode]`) → `None`

Update the power mode, calling callbacks as required.

This is a helper method for use by subclasses.

Parameters

power_mode – the new power mode of the component. This can be `None`, in which case the internal value is updated but no callback is called. This is useful to ensure that the callback is called next time a real value is pushed.

component_power_mode_changed(*power_mode*: `ska_tango_base.control_model.PowerMode`) → `None`

Handle notification that the component's power mode has changed.

This is a callback hook, to be passed to the managed component.

Parameters

power_mode – the new power mode of the component

property power_mode: `Optional[ska_tango_base.control_model.PowerMode]`

Return the power mode of this component manager.

Returns

the power mode of this component manager.

update_component_fault(*faulty*: `Optional[bool]`) → `None`

Update the component fault status, calling callbacks as required.

This is a helper method for use by subclasses.

Parameters

faulty – whether the component has faulted. If `False`, then this is a notification that the component has *recovered* from a fault.

component_fault_changed(*faulty*: `bool`) → `None`

Handle notification that the component's fault status has changed.

This is a callback hook, to be passed to the managed component.

Parameters

faulty – whether the component has faulted. If `False`, then this is a notification that the component has *recovered* from a fault.

property faulty: `Optional[bool]`

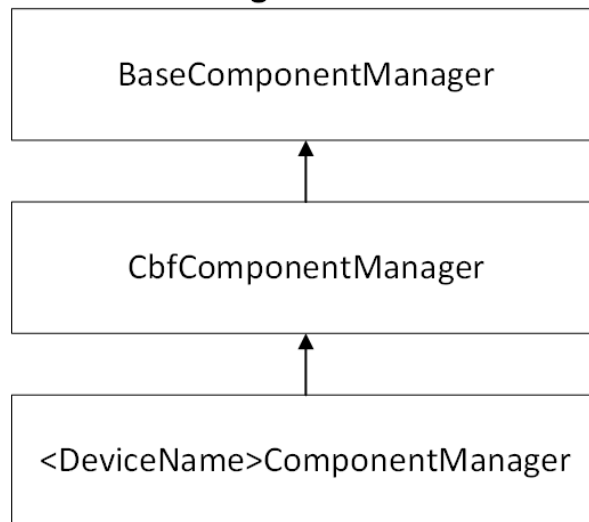
Return whether this component manager is currently experiencing a fault.

Returns

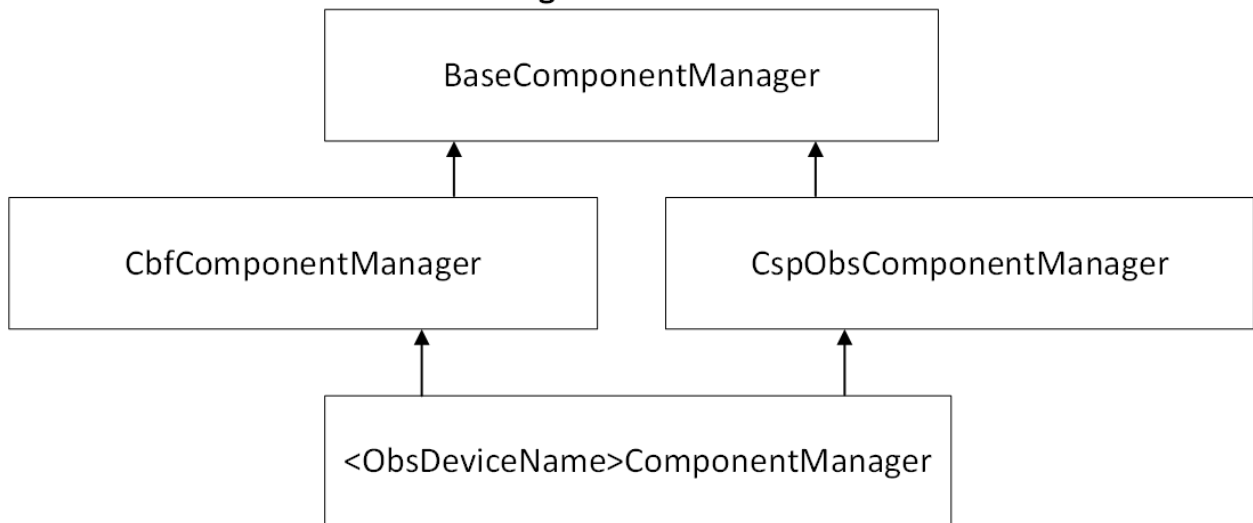
whether this component manager is currently experiencing a fault.

The MCS contains two types of Tango devices: observing and non-observing. Non-observing devices contain only an `op_state_model` while observing devices contain both an `op_state_model` and `obs_state_model`. As shown in the inheritance diagram below, non-observing devices inherit from `CbfComponentManager` while observing devices inherit from `CbfComponentManager` and `CspObsComponentManager`.

Non-Observing Device Inheritance



Observing Device Inheritance



6.2 CbfController

6.2.1 CbfController Class

class `ska_mid_cbf_mcs.controller.controller_device.CbfController(*args: Any, **kwargs: Any)`

Bases: `SKAController`

CbfController TANGO device class. Primary point of contact for monitoring and control of Mid.CBF. Implements state and mode indicators, and a set of state transition commands.

init_command_objects() → `None`

Sets up the command objects

get_num_capabilities() → `None`

Get number of capabilities for `_init_Device`. If property not found in db, then assign a default amount(197,27,16)

class `InitCommand(*args: Any, **kwargs: Any)`

Bases: `InitCommand`

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for device initialisation. :return: A tuple containing a return code and a string message indicating status. The message is for information purpose only. :return: (ResultCode, str)

always_executed_hook() → `None`

Hook to be executed before any command.

create_component_manager() → `ControllerComponentManager`

Create and return a component manager for this device.

Returns

a component manager for this device.

delete_device() → `None`

Unsubscribe to events, turn all the subarrays, VCCs and FSPs off

read_commandProgress() → `int`

Return commandProgress attribute: percentage progress implemented for commands that result in state/mode transitions for a large number of components and/or are executed in stages (e.g power up, power down)

read_receptorToVcc() → `List[str]`

Return 'receptorID:vccID'

read_vccToReceptor() → `List[str]`

Return receptorToVcc attribute: 'vccID:receptorID'

read_subarrayconfigID() → `List[str]`

Return subarrayconfigID attribute: ID of subarray config. Used for debug purposes. empty string if subarray is not configured for a scan

read_frequencyOffsetK() → `List[int]`

Return frequencyOffsetK attribute: array of integers reporting receptors in subarray

write_frequencyOffsetK(value: List[int]) → `None`

Set frequencyOffsetK attribute

read_frequencyOffsetDeltaF() → `List[int]`

Return frequencyOffsetDeltaF attribute: Frequency offset (delta f) of all 197 receptors as an array of ints.

write_frequencyOffsetDeltaF(value: `List[int]`) → `None`

Set the frequencyOffsetDeltaF attribute

write_simulationMode(value: `ska_tango_base.control_model.SimulationMode`) → `None`

Set the Simulation Mode of the device.

Parameters

value – `SimulationMode`

class OnCommand(*args: `Any`, **kwargs: `Any`)

Bases: `OnCommand`

A class for the CbfController's On() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for On() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class OffCommand(*args: `Any`, **kwargs: `Any`)

Bases: `OffCommand`

A class for the CbfController's Off() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for Off() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class StandbyCommand(*args: `Any`, **kwargs: `Any`)

Bases: `StandbyCommand`

A class for the CbfController's Standby() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for Standby() command functionality. Turn off subarray, vcc, fsp, turn CbfController to standby

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

6.2.2 ControllerComponentManager Class

```
class ska_mid_cbf_mcs.controller.controller_component_manager.ControllerComponentManager(*args:
Any,
**kwargs:
Any)
```

Bases: *CbfComponentManager*

A component manager for the CbfController device.

start_communicating() → *None*

Establish communication with the component, then start monitoring.

stop_communicating() → *None*

Stop communication with the component

on() → *Tuple*[ska_tango_base.commands.ResultCode, *str*]

Turn on the controller and its subordinate devices

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(*ResultCode*, *str*)

off() → *Tuple*[ska_tango_base.commands.ResultCode, *str*]

Turn off the controller and its subordinate devices

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(*ResultCode*, *str*)

standby() → *Tuple*[ska_tango_base.commands.ResultCode, *str*]

Turn the controller into low power standby mode

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(*ResultCode*, *str*)

6.2.3 TalonDxComponentManager Class

The *TalonDxComponentManager* is used to configure and start up Tango device servers on the Talon boards. These actions are performed during the On command of the *CbfController*. Note that these actions are not executed when the *simulationMode* of the *CbfController* is set to 1 (this is the default). Prior to sending the On command to the *CbfController*, the *simulationMode* should be set to 0 if it is desired to test the command with the Talon boards in the loop.

```
class ska_mid_cbf_mcs.controller.talondx_component_manager.TalonDxComponentManager(talondx_config_path:
                                                                    str,
                                                                    hw_config_path:
                                                                    str,
                                                                    simula-
                                                                    tion_mode:
                                                                    ska_tango_base.control_m
                                                                    logger:
                                                                    Logger)
```

Bases: `object`

A component manager for the Talon-DX boards. Used to configure and start the Tango applications on the HPS of each board.

configure_talons() → `ska_tango_base.commands.ResultCode`

Performs all actions to configure the Talon boards after power on and start the HPS device servers. This includes: copying the device server binaries and FPGA bitstream to the Talon boards, starting the HPS master device server and sending the configure command to each DsHpsMaster.

Returns

`ResultCode.FAILED` if any operations failed, else `ResultCode.OK`

_setup_tango_host_file() → `None`

Copy the `hps_master_mcs.sh` file from `mnt` into `mnt/talondx-config`

Returns

`ResultCode.OK` if all artifacts were copied successfully, otherwise `ResultCode.FAILED`

_secure_copy(*ssh_client: paramiko.SSHClient, src: str, dest: str*) → `None`

Execute a secure file copy to the specified target address.

Parameters

- **ssh_client** – SSH client for the Talon board we are trying to SCP to
- **src** – Source file path
- **dest** – Destination file path

Raises

SCPException – if the file copy fails

_configure_talon_networking() → `ska_tango_base.commands.ResultCode`

Configure the networking of the boards including DNS nameserver and ifconfig for default gateway

Returns

`ResultCode.OK` if all artifacts were copied successfully, otherwise `ResultCode.FAILED`

_copy_binaries_and_bitstream() → `ska_tango_base.commands.ResultCode`

Copy the relevant device server binaries and FPGA bitstream to each Talon board.

Returns

`ResultCode.OK` if all artifacts were copied successfully, otherwise `ResultCode.FAILED`

_start_hps_master() → `ska_tango_base.commands.ResultCode`

Start the DsHpsMaster on each Talon board.

Returns

`ResultCode.OK` if all HPS masters were started successfully, otherwise `ResultCode.FAILED`

_create_hps_master_device_proxies() → ska_tango_base.commands.ResultCode

Attempt to create a device proxy to each DsHpsMaster device.

Returns

ResultCode.OK if all proxies were created successfully, otherwise ResultCode.FAILED

_configure_hps_master() → ska_tango_base.commands.ResultCode

Send the configure command to all the DsHpsMaster devices.

Returns

ResultCode.OK if all configure commands were sent successfully, otherwise ResultCode.FAILED

6.3 CbfSubarray

6.3.1 CbfSubarray Class

6.3.2 CbfSubarray Component Class

6.4 Fsp

6.4.1 Fsp Class

class ska_mid_cbf_mcs.fsp.fsp_device.**Fsp**(*args: Any, **kwargs: Any)

Bases: SKACapability

Fsp TANGO device class for the prototype

init_command_objects() → None

Sets up the command objects

always_executed_hook() → None

Hook to be executed before any commands.

create_component_manager() → *FspComponentManager*

Create and return a component manager for this device.

Returns

a component manager for this device.

delete_device() → None

Hook to delete device.

write_simulationMode(value: ska_tango_base.control_model.SimulationMode) → None

Set the simulation mode of the device.

Parameters

value – SimulationMode

read_functionMode() → tango.DevEnum

Read the functionMode attribute.

Returns

a DevEnum representing the mode.

Return type

tango.DevEnum

read_subarrayMembership() → List[int]

Read the subarrayMembership attribute.

Returns

an array of affiliations of the FSP.

Return type

List[int]

read_scanID() → int

Read the scanID attribute.

Returns

the scanID attribute.

Return type

int

read_configID() → str

Read the configID attribute.

Returns

the configID attribute.

Return type

str

write_configID(value: str) → None

Write the configID attribute.

Parameters

value – the configID value.

read_jonesMatrix() → str

Read the jonesMatrix attribute.

Returns

the jonesMatrix attribute.

Return type

string

read_delayModel() → str

Read the delayModel attribute.

Returns

the delayModel attribute.

Return type

string

read_timingBeamWeights() → str

Read the timingBeamWeights attribute.

Returns

the timingBeamWeights attribute.

Return type

string

```
class InitCommand(*args: Any, **kwargs: Any)
    Bases: InitCommand
    A class for the Fsp's init_device() "command".
    do() → Tuple[ska_tango_base.commands.ResultCode, str]
        Stateless hook for device initialisation.
        Returns
            A tuple containing a return code and a string message indicating status. The message is for
            information purpose only.
        Return type
            (ResultCode, str)

class OnCommand(*args: Any, **kwargs: Any)
    Bases: OnCommand
    A class for the Fsp's On() command.
    do() → Tuple[ska_tango_base.commands.ResultCode, str]
        Stateless hook for On() command functionality.
        Returns
            A tuple containing a return code and a string message indicating status. The message is for
            information purpose only.
        Return type
            (ResultCode, str)

class OffCommand(*args: Any, **kwargs: Any)
    Bases: OffCommand
    A class for the Fsp's Off() command.
    do() → Tuple[ska_tango_base.commands.ResultCode, str]
        Stateless hook for Off() command functionality.
        Returns
            A tuple containing a return code and a string message indicating status. The message is for
            information purpose only.
        Return type
            (ResultCode, str)

class StandbyCommand(*args: Any, **kwargs: Any)
    Bases: StandbyCommand
    A class for the Fsp's Standby() command.
    do() → Tuple[ska_tango_base.commands.ResultCode, str]
        Stateless hook for Standby() command functionality.
        Returns
            A tuple containing a return code and a string message indicating status. The message is for
            information purpose only.
        Return type
            (ResultCode, str)

class SetFunctionModeCommand(*args: Any, **kwargs: Any)
    Bases: ResponseCommand
    A class for the Fsp's SetFunctionMode() command.
```


do(*argin: str*) → Tuple[[ska_tango_base.commands.ResultCode](#), *str*]

Stateless hook for SetFunctionMode() command functionality.

Parameters

argin – one of ‘IDLE’, ‘CORR’, ‘PSS-BF’, ‘PST-BF’, or ‘VLBI’

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), *str*)

SetFunctionMode(*argin: str*) → [None](#)

Set the Fsp Function Mode, either IDLE, CORR, PSS-BF, PST-BF, or VLBI. If IDLE set the pss, pst, corr and vlbi devices to DISABLE. Otherwise, turn one of them ON according to argin, and all others DISABLE.

Parameters

argin – one of ‘IDLE’, ‘CORR’, ‘PSS-BF’, ‘PST-BF’, or ‘VLBI’

is_SetFunctionMode_allowed() → [bool](#)

Determine if SetFunctionMode is allowed (allowed if FSP state is ON).

Returns

if SetFunctionMode is allowed

Return type

[bool](#)

class AddSubarrayMembershipCommand(*args: *Any*, **kwargs: *Any*)

Bases: [ResponseCommand](#)

A class for the Fsp’s AddSubarrayMembership() command.

do(*argin: int*) → Tuple[[ska_tango_base.commands.ResultCode](#), *str*]

Stateless hook for AddSubarrayMembership() command functionality.

Parameters

argin – an integer representing the subarray affiliation

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), *str*)

AddSubarrayMembership(*argin: str*) → [None](#)

Add a subarray to the subarrayMembership list.

Parameters

argin – an integer representing the subarray affiliation

is_AddSubarrayMembership_allowed() → [bool](#)

Determine if AddSubarrayMembership is allowed (allowed if FSP state is ON).

Returns

if AddSubarrayMembership is allowed

Return type

[bool](#)

class RemoveSubarrayMembershipCommand(*args: *Any*, **kwargs: *Any*)

Bases: ResponseCommand

A class for the Fsp's RemoveSubarrayMembership() command.

do(argin: *int*) → Tuple[*ska_tango_base.commands.ResultCode*, *str*]

Stateless hook for RemoveSubarrayMembership() command functionality.

Parameters

argin – an integer representing the subarray affiliation

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(*ResultCode*, *str*)

RemoveSubarrayMembership(argin: *str*) → *None*

Remove subarray from the subarrayMembership list. If subarrayMembership is empty after removing (no subarray is using this FSP), set function mode to empty.

Parameters

argin – an integer representing the subarray affiliation

is_RemoveSubarrayMembership_allowed() → *bool*

Determine if RemoveSubarrayMembership is allowed (allowed if FSP state is ON).

Returns

if RemoveSubarrayMembership is allowed

Return type

bool

getConfigID() → *str*

Get the configID for all the fspCorrSubarray

Returns

the configID

Return type

str

class UpdateJonesMatrixCommand(*args: *Any*, **kwargs: *Any*)

Bases: ResponseCommand

A class for the Fsp's UpdateJonesMatrix() command.

do(argin: *str*) → Tuple[*ska_tango_base.commands.ResultCode*, *str*]

Stateless hook for UpdateJonesMatrix() command functionality.

Parameters

argin – the jones matrix data

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(*ResultCode*, *str*)

UpdateJonesMatrix(argin: *str*) → *None*

Update the FSP's jones matrix (serialized JSON object)

Parameters

argin – the jones matrix data

is_UpdateJonesMatrix_allowed() → bool

Determine if UpdateJonesMatrix is allowed (allowed if FSP state is ON and ObsState is READY OR SCANNING).

Returns

if UpdateJonesMatrix is allowed

Return type

bool

class UpdateDelayModelCommand(*args: Any, **kwargs: Any)

Bases: ResponseCommand

A class for the Fsp's UpdateDelayModel() command.

do(argin: str) → Tuple[ska_tango_base.commands.ResultCode, str]

Stateless hook for UpdateDelayModel() command functionality.

Parameters

argin – the delay model data

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(ResultCode, str)

UpdateDelayModel(argin: str) → None

Update the FSP's delay model (serialized JSON object)

Parameters

argin – the delay model data

is_UpdateDelayModel_allowed() → bool

Determine if UpdateDelayModel is allowed (allowed if FSP state is ON and ObsState is READY OR SCANNING).

Returns

if UpdateDelayModel is allowed

Return type

bool

class UpdateTimingBeamWeightsCommand(*args: Any, **kwargs: Any)

Bases: ResponseCommand

A class for the Fsp's UpdateTimingBeamWeights() command.

do(argin: str) → Tuple[ska_tango_base.commands.ResultCode, str]

Stateless hook for UpdateTimingBeamWeights() command functionality.

Parameters

argin – the timing beam weight data

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(ResultCode, str)

UpdateTimingBeamWeights(argin: str) → None

Update the FSP's timing beam weights (serialized JSON object)

Parameters

argin – the timing beam weight data

is_UpdateTimingBeamWeights_allowed() → bool

Determine if UpdateTimingBeamWeights is allowed (allowed if FSP state is ON and ObsState is READY OR SCANNING).

Returns

if UpdateTimingBeamWeights is allowed

Return type

bool

6.4.2 FspComponentManager Class

class ska_mid_cbf_mcs.fsp.fsp_component_manager.**FspComponentManager**(*args: Any, **kwargs: Any)

Bases: *CbfComponentManager*

A component manager for the Fsp device.

property subarray_membership: List[int]

Subarray Membership

Returns

an array of affiliations of the FSP.

Return type

List[int]

property function_mode: tango.DevEnum

Function Mode

Returns

the Fsp function mode

Return type

tango.DevEnum

property jones_matrix: str

Jones Matrix

Returns

the jones matrix

Return type

str

property delay_model: str

Delay Model

Returns

the delay model

Return type

str

property timing_beam_weights: str

Timing Beam Weights

Returns

the timing beam weights

Return type

`str`

property simulation_mode: `ska_tango_base.control_model.SimulationMode`

Get the simulation mode of the component manager.

Returns

simulation mode of the component manager

start_communicating() → `None`

Establish communication with the component, then start monitoring.

stop_communicating() → `None`

Stop communication with the component

remove_subarray_membership(*argin: int*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Remove subarray from the subarrayMembership list. If subarrayMembership is empty after removing (no subarray is using this FSP), set function mode to empty.

Parameters

argin – an integer representing the subarray affiliation

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

add_subarray_membership(*argin: int*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Add a subarray to the subarrayMembership list.

Parameters

argin – an integer representing the subarray affiliation

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

on() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Turn on the fsp and its subordinate devices

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

off() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Turn off the fsp and its subordinate devices

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

standby() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Put the fsp into low power standby mode

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

set_function_mode(*argin*: `str`) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Put the fsp into low power standby mode

Parameters

argin – one of ‘IDLE’, ‘CORR’, ‘PSS-BF’, ‘PST-BF’, or ‘VLBI’

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

update_jones_matrix(*argin*: `str`) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Update the FSP’s jones matrix (serialized JSON object)

Parameters

argin – the jones matrix data

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

update_delay_model(*argin*: `str`) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Update the FSP’s delay model (serialized JSON object)

Parameters

argin – the delay model data

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

update_timing_beam_weights(*argin*: `str`) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Update the FSP’s timing beam weights (serialized JSON object)

Parameters

argin – the timing beam weight data

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

get_fsp_corr_config_id() → `str`

Get the configID for all the fspCorrSubarray

Returns

the configID

Return type

`str`

6.4.3 FspCorrSubarray Class

class `ska_mid_cbf_mcs.fsp.fsp_corr_subarray_device.FspCorrSubarray(*args: Any, **kwargs: Any)`

Bases: `CspSubElementObsDevice`

FspCorrSubarray TANGO device class for the FspCorrSubarray prototype

init_command_objects() → `None`

Sets up the command objects

class `InitCommand(*args: Any, **kwargs: Any)`

Bases: `InitCommand`

A class for the FspCorrSubarray's `init_device()` "command".

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for device initialisation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

always_executed_hook() → `None`

Hook to be executed before any commands.

create_component_manager() → *FspCorrSubarrayComponentManager*

Create and return a component manager for this device.

Returns

a component manager for this device.

delete_device() → `None`

Hook to delete device.

read_receptors() → `List[int]`

Read the receptors attribute.

Returns

the list of receptors

Return type

`List[int]`

read_frequencyBand() → tango.DevEnum

Read the frequencyBand attribute.

Returns

the frequency band

Return type

tango.DevEnum

read_band5Tuning() → List[float]

Read the band5Tuning attribute.

Returns

the band5Tuning attribute (array of float, first element corresponds to the first stream, second to the second stream).

Return type

List[float]

read_frequencyBandOffsetStream1() → int

Read the frequencyBandOffsetStream1 attribute.

Returns

the frequencyBandOffsetStream1 attribute

Return type

int

read_frequencyBandOffsetStream2() → int

Read the frequencyBandOffsetStream2 attribute.

Returns

the frequencyBandOffsetStream2 attribute.

Return type

int

read_frequencySliceID() → int

Read the frequencySliceID attribute.

Returns

the frequencySliceID attribute.

Return type

int

read_corrBandwidth() → int

Read the corrBandwidth attribute.

Returns

the corrBandwidth attribute (bandwidth to be correlated is <Full Bandwidth>/2^bandwidth).

Return type

int

read_zoomWindowTuning() → int

Read the zoomWindowTuning attribute.

Returns

the zoomWindowTuning attribute

Return type

`int`

read_integrationFactor() → `int`

Read the integrationFactor attribute.

Returns

the integrationFactor attribute (millisecond).

Return type

`int`

read_channelAveragingMap() → `List[List[int]]`

Read the channelAveragingMap attribute.

Returns

the channelAveragingMap attribute. Consists of 2*20 array of integers(20 tuples representing 20* 744 channels). The first element is the ID of the first channel in a channel group. The second element is the averaging factor

Return type

`List[List[int]]`

read_visDestinationAddress() → `str`

Read the visDestinationAddress attribute.

Returns

the visDestinationAddress attribute. (JSON object containing info about current SDP destination addresses being used).

Return type

`str`

write_visDestinationAddress(value: str) → `None`

Write the visDestinationAddress attribute.

Parameters

value – the visDestinationAddress attribute value. (JSON object containing info about current SDP destination addresses being used).

read_fspChannelOffset() → `int`

Read the fspChannelOffset attribute.

Returns

the fspChannelOffset attribute.

Return type

`int`

write_fspChannelOffset(value: int) → `None`

Write the fspChannelOffset attribute.

Parameters

value – the fspChannelOffset attribute value.

read_outputLinkMap() → `List[List[int]]`

Read the outputLinkMap attribute.

Returns

the outputLinkMap attribute.

Return type

List[List[int]]

write_outputLinkMap(*value*: List[List[int]]) → None

Write the outputLinkMap attribute.

Parameters

value – the outputLinkMap attribute value.

read_scanID() → int

Read the scanID attribute.

Returns

the scanID attribute.

Return type

int

write_scanID(*value*: int) → None

Write the scanID attribute.

Parameters

value – the scanID attribute value.

read_configID() → str

Read the configID attribute.

Returns

the configID attribute.

Return type

str

write_configID(*value*: str) → None

Write the configID attribute.

Parameters

value – the configID attribute value.

write_simulationMode(*value*: ska_tango_base.control_model.SimulationMode) → None

Set the simulation mode of the device.

Parameters

value – SimulationMode

class OnCommand(*args: Any, **kwargs: Any)

Bases: OnCommand

A class for the FspCorrSubarray's On() command.

do() → Tuple[ska_tango_base.commands.ResultCode, str]

Stateless hook for On() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(ResultCode, str)

class OffCommand(*args: Any, **kwargs: Any)

Bases: OffCommand

A class for the FspCorrSubarray's Off() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for Off() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class StandbyCommand(*args: *Any*, **kwargs: *Any*)

Bases: `StandbyCommand`

A class for the FspCorrSubarray's Standby() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for Standby() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class ConfigureScanCommand(*args: *Any*, **kwargs: *Any*)

Bases: `ConfigureScanCommand`

A class for the FspCorrSubarray's ConfigureScan() command.

do(*argin*: `str`) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for ConfigureScan() command functionality.

Parameters

argin (`str`) – The configuration as JSON formatted string

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

Raises

`CommandError` if the configuration data validation fails.

validate_input(*argin*: `str`) → `Tuple[bool, str]`

Validate the configuration parameters against allowed values, as needed.

Parameters

argin – The JSON formatted string with configuration for the device. :type argin: 'DevString'

Returns

A tuple containing a boolean and a string message.

Return type

(`bool`, `str`)

class ScanCommand(*args: *Any*, **kwargs: *Any*)

Bases: `ScanCommand`

A class for the FspCorrSubarrFspCorrSubarrayay's Scan() command.

do(*argin*: `str`) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for Scan() command functionality.

Parameters

argin (`str`) – The scan ID

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

Raises

`CommandError` if the configuration data validation fails.

class `EndScanCommand(*args: Any, **kwargs: Any)`

Bases: `EndScanCommand`

A class for the `FspCorrSubarray`'s `Scan()` command.

do() → `Tuple[skatango_base.commands.ResultCode, str]`

Stateless hook for `Scan()` command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

Raises

`CommandError` if the configuration data validation fails.

class `GoToIdleCommand(*args: Any, **kwargs: Any)`

Bases: `GoToIdleCommand`

A class for the `FspCorrSubarray`'s `GoToIdle` command.

do() → `Tuple[skatango_base.commands.ResultCode, str]`

Stateless hook for `GoToIdle()` command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

is_getLinkAndAddress_allowed() → `bool`

Determine if `getLinkAndAddress` is allowed (allowed if destination addresses are received, meaning `outLinkMap` also received (checked in `subarray validate scan`)).

Returns

if `getLinkAndAddress` is allowed

Return type

`bool`

getLinkAndAddress(argin: int) → `str`

Get output link and destination addresses in JSON based on a channel ID.

Parameters

argin – the channel id.

Returns

the output link and destination addresses in JSON.

Return type

`str`

6.4.4 FspCorrSubarrayComponentManager Class

```
class ska_mid_cbf_mcs.fsp.fsp_corr_subarray_component_manager.FspCorrSubarrayComponentManager(*args:
Any,
**kwargs:
Any)
```

Bases: [CbfComponentManager](#), [CspObsComponentManager](#)

A component manager for the FspCorrSubarray device.

property frequency_band: [tango.DevEnum](#)

Frequency Band

Returns

the frequency band

Return type

[tango.DevEnum](#)

property stream_tuning: [List\[float\]](#)

Band 5 Tuning

Returns

an array of float, (first element corresponds to the first stream, second to the second stream).

Return type

[List\[float\]](#)

property frequency_band_offset_stream1: [int](#)

Frequency Band Offset Stream 1

Returns

the frequency band offset for stream 1

Return type

[int](#)

property frequency_band_offset_stream2: [int](#)

Frequency Band Offset Stream 2

Returns

the frequency band offset for stream 2

Return type

[int](#)

property frequency_slice_id: [int](#)

Frequency Slice ID

Returns

the frequency slice id

Return type

[int](#)

property bandwidth: [int](#)

Bandwidth

Returns

the corr bandwidth (bandwidth to be correlated is $\text{Full Bandwidth} / 2^{\text{bandwidth}}$).

Return type

`int`

property integration_factor: `int`

Integration Factor

Returns

the integration factor

Return type

`int`

property fsp_channel_offset: `int`

FSP Channel Offset

Returns

the FSP channel offset

Return type

`int`

property vis_destination_address: `str`

VIS Destination Address

Returns

JSON string containing info about current SDP destination addresses being used

Return type

`str`

property output_link_map: `List[List[int]]`

Output Link Map

Returns

the output link map

Return type

`List[List[int]]`

property channel_averaging_map: `List[List[int]]`

Channel Averaging Map

Returns

the channel averaging map. Consists of 2*20 array of integers(20 tuples representing 20*744 channels). The first element is the ID of the first channel in a channel group. The second element is the averaging factor

Return type

`List[List[int]]`

property zoom_window_tuning: `int`

Zoom Window Tuning

Returns

the zoom window tuning

Return type

`int`

property config_id: `str`

Config ID

Returns

the config id

Return type

str

property scan_id: int

Scan ID

Returns

the scan id

Return type

int

property receptors: List[int]

Receptors

Returns

list of receptor ids

Return type

List[int]

property simulation_mode: ska_tango_base.control_model.SimulationMode

Get the simulation mode of the component manager.

Returns

simulation mode of the component manager

start_communicating() → None

Establish communication with the component, then start monitoring.

stop_communicating() → None

Stop communication with the component

configure_scan(configuration: str) → Tuple[ska_tango_base.commands.ResultCode, str]

Performs the ConfigureScan() command functionality

Parameters

configuration – The configuration as JSON formatted string

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(ResultCode, str)

scan(scan_id: int) → Tuple[ska_tango_base.commands.ResultCode, str]

Performs the Scan() command functionality

Parameters

scan_id – The scan id

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(ResultCode, str)

end_scan() → [Tuple](#)[[ska_tango_base.commands.ResultCode](#), [str](#)]

Performs the EndScan() command functionality

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

go_to_idle() → [Tuple](#)[[ska_tango_base.commands.ResultCode](#), [str](#)]

Performs the GoToIdle() command functionality

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

6.4.5 FspPssSubarray Class

class `ska_mid_cbf_mcs.fsp.fsp_pss_subarray_device.FspPssSubarray(*args: Any, **kwargs: Any)`

Bases: [CspSubElementObsDevice](#)

FspPssSubarray TANGO device class for the FspPssSubarray prototype

init_command_objects() → [None](#)

Sets up the command objects

class `InitCommand(*args: Any, **kwargs: Any)`

Bases: [InitCommand](#)

A class for the FspPssSubarray's init_device() "command".

do() → [Tuple](#)[[ska_tango_base.commands.ResultCode](#), [str](#)]

Stateless hook for device initialisation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

always_executed_hook() → [None](#)

Hook to be executed before any commands.

create_component_manager() → [FspPssSubarrayComponentManager](#)

Create and return a component manager for this device.

Returns

a component manager for this device.

delete_device() → [None](#)

Hook to delete device.

read_receptors() → [List](#)[[int](#)]

Read the receptors attribute.

Returns

the receptors attribute.

Return type

List[int]

read_searchBeams() → List[str]

Read the searchBeams attribute.

Returns

the searchBeams attribute.

Return type

List[str]

read_searchBeamID() → List[int]

Read the searchBeamID attribute.

Returns

the searchBeamID attribute.

Return type

List[int]

read_searchWindowID() → List[int]

Read the searchWindowID attribute.

Returns

the searchWindowID attribute.

Return type

List[int]

read_outputEnable() → bool

Read the outputEnable attribute. Used to enable/disable transmission of the output products.

Returns

the outputEnable attribute.

Return type

bool

read_scanID() → int

Read the scanID attribute.

Returns

the scanID attribute.

Return type

int

write_scanID(value: int) → None

Write the scanID attribute.

Parameters

value – the scanID attribute value.

read_configID() → str

Read the configID attribute.

Returns

the configID attribute.

Return type

`str`

write_configID(*value: str*) → `None`

Write the configID attribute.

Parameters

value – the configID attribute value.

class OnCommand(*args: *Any*, **kwargs: *Any*)

Bases: `OnCommand`

A class for the FspPssSubarray's On() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for On() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class OffCommand(*args: *Any*, **kwargs: *Any*)

Bases: `OffCommand`

A class for the FspPssSubarray's Off() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for Off() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class StandbyCommand(*args: *Any*, **kwargs: *Any*)

Bases: `StandbyCommand`

A class for the FspPssSubarray's Standby() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for Standby() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class ConfigureScanCommand(*args: *Any*, **kwargs: *Any*)

Bases: `ConfigureScanCommand`

A class for the FspPssSubarray's ConfigureScan() command.

do(*argin: str*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for ConfigureScan() command functionality.

Parameters

argin (*str*) – The configuration as JSON formatted string.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

Raises

`CommandError` if the configuration data validation fails.

validate_input(*argin*: `str`) → `Tuple[bool, str]`

Validate the configuration parameters against allowed values, as needed.

Parameters

argin – The JSON formatted string with configuration for the device. :type argin: ‘DevString’

Returns

A tuple containing a boolean and a string message.

Return type

(`bool`, `str`)

class ScanCommand(*args: `Any`, **kwargs: `Any`)

Bases: `ScanCommand`

A class for the FspPssSubarray’s Scan() command.

do(*argin*: `str`) → `Tuple[skatango_base.commands.ResultCode, str]`

Stateless hook for Scan() command functionality.

Parameters

argin (`str`) – The scan ID

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

Raises

`CommandError` if the configuration data validation fails.

class EndScanCommand(*args: `Any`, **kwargs: `Any`)

Bases: `EndScanCommand`

A class for the FspPssSubarray’s Scan() command.

do() → `Tuple[skatango_base.commands.ResultCode, str]`

Stateless hook for Scan() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

Raises

`CommandError` if the configuration data validation fails.

class GoToIdleCommand(*args: `Any`, **kwargs: `Any`)

Bases: `GoToIdleCommand`

A class for the FspPssSubarray’s GoToIdle command.

do() → `Tuple[skatango_base.commands.ResultCode, str]`

Stateless hook for GoToIdle() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

6.4.6 FspPssSubarrayComponentManager Class

```
class ska_mid_cbf_mcs.fsp.fsp_pss_subarray_component_manager.FspPssSubarrayComponentManager(*args:
Any,
**kwargs:
Any)
```

Bases: `CbfComponentManager`, `CspObsComponentManager`

A component manager for the FspPssSubarray device.

property scan_id: `int`

Scan ID

Returns

the scan id

Return type

`int`

property config_id: `str`

Config ID

Returns

the config id

Return type

`str`

property fsp_id: `int`

Fsp ID

Returns

the fsp id

Return type

`int`

property search_window_id: `int`

Search Window ID

Returns

the search window id

Return type

`int`

property search_beams: `List[str]`

Search Beams

Returns

search beams

Return type

`List[str]`

property search_beam_id: `List[int]`

Search Beam ID

Returns

search beam id

Return type

`List[int]`

property output_enable: `bool`

Output Enable

Returns

output enable

Return type

`bool`

property receptors: `List[int]`

Receptors

Returns

list of receptor ids

Return type

`List[int]`

start_communicating() `→ None`

Establish communication with the component, then start monitoring.

stop_communicating() `→ None`

Stop communication with the component

configure_scan(configuration: str) `→ Tuple[ska_tango_base.commands.ResultCode, str]`

Performs the ConfigureScan() command functionality

Parameters

configuration – The configuration as JSON formatted string

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

`(ResultCode, str)`

scan(scan_id: int) `→ Tuple[ska_tango_base.commands.ResultCode, str]`

Performs the Scan() command functionality

Parameters

scan_id – The scan id

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

`(ResultCode, str)`

end_scan() `→ Tuple[ska_tango_base.commands.ResultCode, str]`

Performs the EndScan() command functionality

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

go_to_idle() → `Tuple[skatango_base.commands.ResultCode, str]`

Performs the GoToIdle() command functionality

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

6.4.7 FspPstSubarray Class

class `skatango_base.commands.fsp.fsp_pst_subarray_device.FspPstSubarray(*args: Any, **kwargs: Any)`

Bases: `CspSubElementObsDevice`

FspPstSubarray TANGO device class for the FspPstSubarray prototype

init_command_objects() → `None`

Sets up the command objects

class `InitCommand(*args: Any, **kwargs: Any)`

Bases: `InitCommand`

A class for the FspPstSubarray's init_device() "command".

do() → `Tuple[skatango_base.commands.ResultCode, str]`

Stateless hook for device initialisation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

always_executed_hook() → `None`

Hook to be executed before any commands.

create_component_manager() → *FspPstSubarrayComponentManager*

Create and return a component manager for this device.

Returns

a component manager for this device.

delete_device() → `None`

Hook to delete device.

read_outputEnable() → `bool`

Read the outputEnable attribute. Used to enable/disable transmission of the output products.

Returns

the outputEnable attribute.

Return type

`bool`

read_receptors() → `List[int]`

Read the receptors attribute.

Returns

the list of receptors.

Return type

`List[int]`

write_receptors(value: `List[int]`) → `None`

Write the receptors attribute.

Parameters

value – the receptors attribute value.

read_timingBeams() → `List[str]`

Read the timingBeams attribute.

Returns

the timingBeams attribute.

Return type

`List[int]`

read_timingBeamID() → `List[int]`

Read the list of Timing Beam IDs.

Returns

the timingBeamID attribute.

Return type

`List[int]`

read_scanID() → `int`

Read the scanID attribute.

Returns

the scanID attribute.

Return type

`int`

write_scanID(value: `int`) → `None`

Write the scanID attribute.

Parameters

value – the scanID attribute value.

class OnCommand(*args: `Any`, **kwargs: `Any`)

Bases: `OnCommand`

A class for the FspPstSubarray's On() command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for On() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

class [OffCommand](#)(*args: [Any](#), **kwargs: [Any](#))

Bases: [OffCommand](#)

A class for the FspPstSubarray's Off() command.

do() → [Tuple](#)[[ska_tango_base.commands.ResultCode](#), [str](#)]

Stateless hook for Off() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

class [StandbyCommand](#)(*args: [Any](#), **kwargs: [Any](#))

Bases: [StandbyCommand](#)

A class for the FspPstSubarray's Standby() command.

do() → [Tuple](#)[[ska_tango_base.commands.ResultCode](#), [str](#)]

Stateless hook for Standby() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

class [ConfigureScanCommand](#)(*args: [Any](#), **kwargs: [Any](#))

Bases: [ConfigureScanCommand](#)

A class for the FspPstSubarray's ConfigureScan() command.

do(*argin*: [str](#)) → [Tuple](#)[[ska_tango_base.commands.ResultCode](#), [str](#)]

Stateless hook for ConfigureScan() command functionality.

Parameters

argin ([str](#)) – The configuration as JSON formatted string

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

Raises

[CommandError](#) if the configuration data validation fails.

validate_input(*argin*: [str](#)) → [Tuple](#)[[bool](#), [str](#)]

Validate the configuration parameters against allowed values, as needed.

Parameters

argin – The JSON formatted string with configuration for the device. :type argin: 'DevString'

Returns

A tuple containing a boolean and a string message.

Return type

([bool](#), [str](#))


```
class ScanCommand(*args: Any, **kwargs: Any)
    Bases: ScanCommand
    A class for the FspPstSubarray's Scan() command.
    do(argin: str) → Tuple[skatango_base.commands.ResultCode, str]
        Stateless hook for Scan() command functionality.
        Parameters
            argin (str) – The scan ID
        Returns
            A tuple containing a return code and a string message indicating status. The message is for
            information purpose only.
        Return type
            (ResultCode, str)
        Raises
            CommandError if the configuration data validation fails.

class EndScanCommand(*args: Any, **kwargs: Any)
    Bases: EndScanCommand
    A class for the FspPstSubarray's EndScan() command.
    do() → Tuple[skatango_base.commands.ResultCode, str]
        Stateless hook for Scan() command functionality.
        Returns
            A tuple containing a return code and a string message indicating status. The message is for
            information purpose only.
        Return type
            (ResultCode, str)
        Raises
            CommandError if the configuration data validation fails.

class GoToIdleCommand(*args: Any, **kwargs: Any)
    Bases: GoToIdleCommand
    A class for the FspPstSubarray's GoToIdle command.
    do() → Tuple[skatango_base.commands.ResultCode, str]
        Stateless hook for GoToIdle() command functionality.
        Returns
            A tuple containing a return code and a string message indicating status. The message is for
            information purpose only.
        Return type
            (ResultCode, str)
```

6.4.8 FspPstSubarrayComponentManager Class

```
class skamidcbfmcs.fsp.fsp_pst_subarray_component_manager.FspPstSubarrayComponentManager(*args:
    Any,
    **kwargs:
    Any)

    Bases: CbfComponentManager, CspObsComponentManager
    A component manager for the FspPstSubarray device.
```

property fsp_id: `int`

Fsp ID

Returns

the fsp id

Return type

`int`

property timing_beams: `List[str]`

Timing Beams

Returns

the timing beams

Return type

`List[str]`

property timing_beam_id: `List[int]`

Timing Beam ID

Returns

list of timing beam ids

Return type

`List[int]`

property receptors: `List[int]`

Receptors

Returns

list of receptor ids

Return type

`List[int]`

property scan_id: `int`

Scan ID

Returns

the scan id

Return type

`int`

property output_enable: `bool`

Output Enable

Returns

output enable

Return type

`bool`

start_communicating() \rightarrow `None`

Establish communication with the component, then start monitoring.

stop_communicating() \rightarrow `None`

Stop communication with the component

configure_scan(*configuration: str*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Performs the ConfigureScan() command functionality

Parameters

configuration – The configuration as JSON formatted string

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

scan(*scan_id: int*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Performs the Scan() command functionality

Parameters

scan_id – The scan id

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

end_scan() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Performs the EndScan() command functionality

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

go_to_idle() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Performs the GoToIdle() command functionality

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

6.5 Vcc

6.5.1 VCC Class

class `ska_mid_cbf_mcs.vcc.vcc_device.Vcc`(*args: *Any*, **kwargs: *Any*)

Bases: `CspSubElementObsDevice`

Vcc TANGO device class for the prototype

init_command_objects() → `None`

Sets up the command objects

create_component_manager() → *VccComponentManager*

always_executed_hook() → *None*

Hook to be executed before any commands.

delete_device() → *None*

Hook to delete device.

write_simulationMode(*value: ska_tango_base.control_model.SimulationMode*) → *None*

Set the simulation mode of the device.

Parameters

value – SimulationMode

read_receptorID() → *int*

Read the receptorID attribute.

Returns

the Vcc's receptor id.

Return type

int

write_receptorID(*value: int*) → *None*

Write the receptorID attribute.

Parameters

value – the receptorID value.

read_subarrayMembership() → *int*

Read the subarrayMembership attribute.

Returns

the subarray membership (0 = no affiliation).

Return type

int

write_subarrayMembership(*value: int*) → *None*

Write the subarrayMembership attribute.

Parameters

value – the subarray membership value (0 = no affiliation).

read_frequencyOffsetK() → *int*

Read the frequencyOffsetK attribute.

Returns

the frequency offset k-value

Return type

int

write_frequencyOffsetK(*value: int*) → *None*

Write the frequencyOffsetK attribute.

Parameters

value – the frequency offset k-value

read_frequencyOffsetDeltaF() → `int`

Read the frequencyOffsetDeltaF attribute.

Returns

the frequency offset delta-f value

Return type

`int`

write_frequencyOffsetDeltaF(value: `int`) → `None`

Write the frequencyOffsetDeltaF attribute.

Parameters

value – the frequency offset delta-f value

read_frequencyBand() → `tango.DevEnum`

Read the frequencyBand attribute.

Returns

the frequency band (being observed by the current scan, one of ["1", "2", "3", "4", "5a", "5b"]).

Return type

`tango.DevEnum`

read_band5Tuning() → `List[float]`

Read the band5Tuning attribute.

Returns

the band5Tuning attribute (stream tuning (GHz)).

Return type

list of float

read_frequencyBandOffsetStream1() → `int`

Read the frequencyBandOffsetStream1 attribute.

Returns

the frequencyBandOffsetStream1 attribute.

Return type

`int`

read_frequencyBandOffsetStream2() → `int`

Read the frequencyBandOffsetStream2 attribute.

Returns

the frequencyBandOffsetStream2 attribute.

Return type

`int`

read_dopplerPhaseCorrection() → `List[float]`

Read the dopplerPhaseCorrection attribute.

Returns

the dopplerPhaseCorrection attribute.

Return type

list of float

write_dopplerPhaseCorrection(*value: List[float]*) → *None*

Write the dopplerPhaseCorrection attribute.

Parameters

value – the dopplerPhaseCorrection attribute value.

read_rfiFlaggingMask() → *str*

Read the rfiFlaggingMask attribute.

Returns

the rfiFlaggingMask attribute.

Return type

str/JSON

read_delayModel() → *str*

Read the delayModel attribute.

Returns

the delayModel attribute (delay model coefficients, :return: the delayModel attribute (delay model coefficients,

Returns

the delayModel attribute (delay model coefficients, given per frequency slice).

Return type

list of list of float

read_jonesMatrix() → *str*

Read the jonesMatrix attribute.

Returns

the jonesMatrix attribute (jones matrix values, given per frequency slice).

Return type

str

read_scanID() → *int*

Read the scanID attribute.

Returns

the scanID attribute.

Return type

int

read_configID() → *str*

Read the configID attribute.

Returns

the configID attribute.

Return type

str

class InitCommand(*args: *Any*, **kwargs: *Any*)

Bases: *InitCommand*

A class for the Vcc’s init_device() “command”.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for device initialisation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class OnCommand(*args: *Any*, **kwargs: *Any*)

Bases: `OnCommand`

A class for the Vcc's on command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for device initialisation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class OffCommand(*args: *Any*, **kwargs: *Any*)

Bases: `OffCommand`

A class for the Vcc's off command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for device initialisation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class StandbyCommand(*args: *Any*, **kwargs: *Any*)

Bases: `StandbyCommand`

A class for the Vcc's standby command.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for device initialisation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class ConfigureBandCommand(*args: *Any*, **kwargs: *Any*)

Bases: `ResponseCommand`

A class for the Vcc's ConfigureBand() command.

Turn on the corresponding band device and disable all the others.

do(*argin: str*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for ConfigureBand() command functionality.

Parameters

freq_band_name – the frequency band name

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class `ConfigureScanCommand`(*args: *Any*, **kwargs: *Any*)

Bases: `ConfigureScanCommand`

A class for the Vcc's `ConfigureScan()` command.

do(*argin*: `str`) → `Tuple`[`ska_tango_base.commands.ResultCode`, `str`]

Stateless hook for `ConfigureScan()` command functionality.

Parameters

argin (`str`) – The configuration as JSON formatted string

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

Raises

`CommandError` if the configuration data validation fails.

validate_input(*argin*: `str`) → `Tuple`[`bool`, `str`]

Validate the configuration parameters against allowed values, as needed.

Parameters

argin – The JSON formatted string with configuration for the device. :type argin: 'DevString'

Returns

A tuple containing a boolean and a string message.

Return type

(`bool`, `str`)

class `ScanCommand`(*args: *Any*, **kwargs: *Any*)

Bases: `ScanCommand`

A class for the Vcc's `Scan()` command.

do(*argin*: `str`) → `Tuple`[`ska_tango_base.commands.ResultCode`, `str`]

Stateless hook for `Scan()` command functionality.

Parameters

argin (`str`) – The scan ID as JSON formatted string

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

class `EndScanCommand`(*args: *Any*, **kwargs: *Any*)

Bases: `EndScanCommand`

A class for the Vcc's `EndScan()` command.

do() → `Tuple`[`ska_tango_base.commands.ResultCode`, `str`]

Stateless hook for `EndScan()` command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

class [ObsResetCommand](#)(*args: [Any](#), **kwargs: [Any](#))

Bases: [ObsResetCommand](#)

A class for the VCC's ObsReset command.

do()

Stateless hook for ObsReset() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

class [AbortCommand](#)(*args: [Any](#), **kwargs: [Any](#))

Bases: [AbortCommand](#)

A class for the VCC's Abort command.

do()

Stateless hook for Abort() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

class [GoToIdleCommand](#)(*args: [Any](#), **kwargs: [Any](#))

Bases: [GoToIdleCommand](#)

A class for the Vcc's GoToIdle command.

do() → [Tuple](#)[[ska_tango_base.commands.ResultCode](#), [str](#)]

Stateless hook for GoToIdle() command functionality.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

class [UpdateDopplerPhaseCorrectionCommand](#)(*args: [Any](#), **kwargs: [Any](#))

Bases: [BaseCommand](#)

A class for the Vcc's UpdateDopplerPhaseCorrection() command.

Update Vcc's doppler phase correction.

is_allowed() → [bool](#)

Determine if UpdateDopplerPhaseCorrection is allowed (allowed when Devstate is ON and ObsState is READY OR SCANNING).

Returns

if UpdateDopplerPhaseCorrection is allowed

Return type

[bool](#)

do(argin: [str](#)) → [None](#)

Stateless hook for UpdateDopplerPhaseCorrection() command functionality.

Parameters

argin – the doppler phase correction JSON

class UpdateDelayModelCommand(*args: Any, **kwargs: Any)

Bases: BaseCommand

A class for the Vcc's UpdateDelayModel() command.

Update Vcc's delay model.

is_allowed() → bool

Determine if UpdateDelayModel is allowed (allowed when Devstate is ON and ObsState is READY OR SCANNING).

Returns

if UpdateDelayModel is allowed

Return type

bool

do(argin: str) → None

Stateless hook for UpdateDelayModel() command functionality.

Parameters

argin – the delay model JSON

class UpdateJonesMatrixCommand(*args: Any, **kwargs: Any)

Bases: BaseCommand

A class for the Vcc's UpdateJonesMatrix() command.

Update Vcc's Jones matrix.

is_allowed() → bool

Determine if UpdateJonesMatrix is allowed (allowed when Devstate is ON and ObsState is READY OR SCANNING).

Returns

if UpdateJonesMatrix is allowed

Return type

bool

do(argin: str) → None

Stateless hook for UpdateJonesMatrix() command functionality.

Parameters

argin – the Jones Matrix JSON

class ConfigureSearchWindowCommand(*args: Any, **kwargs: Any)

Bases: ResponseCommand

A class for the Vcc's ConfigureSearchWindow() command.

Configure a search window by sending parameters from the input(JSON) to SearchWindow device. This function is called by the subarray after the configuration has already been validated.

is_allowed() → bool

Determine if ConfigureSearchWindow is allowed (allowed if DevState is ON and ObsState is CONFIGURING)

Returns

if ConfigureSearchWindow is allowed

Return type

bool

validate_input(*argin: str*) → `Tuple[bool, str]`

Validate a search window configuration

Parameters

argin – JSON object with the search window parameters

do(*argin: str*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for ConfigureSearchWindow() command functionality.

Parameters

argin – JSON object with the search window parameters

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

6.5.2 VccComponentManager Class

class `ska_mid_cbf_mcs.vcc.vcc_component_manager.VccComponentManager`(*args: *Any*, **kwargs: *Any*)

Bases: `CbfComponentManager`, `CspObsComponentManager`

Component manager for Vcc class.

property config_id: `str`

Configuration ID

Returns

the configuration ID

property scan_id: `int`

Scan ID

Returns

the scan ID

property receptor_id: `int`

Receptor ID

Returns

the receptor ID

property frequency_offset_k: `int`

Frequency Offset K-value for this receptor

Returns

the frequency offset k-value

property frequency_offset_delta_f: `int`

Frequency Offset Delta-F Value for this receptor

Returns

the frequency offset delta-f value

property frequency_band: `int`

Frequency Band

Returns

the frequency band as the integer index in an array of frequency band labels: ["1", "2", "3", "4", "5a", "5b"]

property stream_tuning: `List[float]`

Band 5 Stream Tuning

Returns

the band 5 stream tuning

property frequency_band_offset_stream1: `int`

Frequency Band Offset Stream 1

Returns

the frequency band offset for stream 1

property frequency_band_offset_stream2: `int`

Frequency Band Offset Stream 2

Returns

the frequency band offset for stream 2, this is only use when band 5 is active

property rfi_flagging_mask: `str`

RFI Flagging Mask

Returns

the RFI flagging mask

property jones_matrix: `str`

Jones Matrix

Returns

the last received Jones matrix

property delay_model: `str`

Delay Model

Returns

the last received delay model

property doppler_phase_correction: `List[float]`

Doppler Phase Correction

Returns

the last received Doppler phase correction array

property simulation_mode: `ska_tango_base.control_model.SimulationMode`

Get the simulation mode of the component manager.

Returns

simulation mode of the component manager

start_communicating() → `None`

Establish communication with the component, then start monitoring.

stop_communicating() → `None`

Stop communication with the component.

on() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Turn on VCC component. This attempts to establish communication with the VCC devices on the HPS.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

Raises

ConnectionError – if unable to connect to HPS VCC devices

off() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Turn off VCC component; currently unimplemented.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

standby() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Turn VCC component to standby; currently unimplemented.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

configure_band(freq_band_name: str) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Configure the corresponding band. At the HPS level, this reconfigures the FPGA to the correct bitstream and enables the respective band device. All other band devices are disabled.

Parameters

freq_band_name – the frequency band name

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

deconfigure() → `None`

Deconfigure scan configuration parameters.

configure_scan(argin: str) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Execute configure scan operation.

Parameters

argin – JSON string with the configure scan parameters

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(`ResultCode`, `str`)

scan(*scan_id: int*) → [Tuple](#)[ska_tango_base.commands.ResultCode, [str](#)]

Begin scan operation.

Parameters

argin – scan ID integer

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

end_scan() → [Tuple](#)[ska_tango_base.commands.ResultCode, [str](#)]

End scan operation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

abort()

Tell the current VCC band device to abort whatever it was doing.

obsreset()

Reset the configuration.

configure_search_window(*argin: str*) → [Tuple](#)[ska_tango_base.commands.ResultCode, [str](#)]

Configure a search window by sending parameters from the input(JSON) to SearchWindow self. This function is called by the subarray after the configuration has already been validated, so the checks here have been removed to reduce overhead.

Parameters

argin – JSON string with the search window parameters

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

([ResultCode](#), [str](#))

update_doppler_phase_correction(*argin: str*) → [None](#)

Update Vcc's doppler phase correction

Parameters

argin – the doppler phase correction JSON string

update_delay_model(*argin: str*) → [None](#)

Update Vcc's delay model

Parameters

argin – the delay model JSON string

update_jones_matrix(*argin: str*) → [None](#)

Update Vcc's jones matrix

Parameters

argin – the jones matrix JSON string

6.6 PowerSwitch

6.6.1 PowerSwitch Device

class `ska_mid_cbf_mcs.power_switch.power_switch_device.PowerSwitch(*args: Any, **kwargs: Any)`

Bases: `SKABaseDevice`

TANGO device class for controlling and monitoring the web power switch that distributes power to the Talon LRUs.

always_executed_hook() → `None`

Hook to be executed before any attribute access or command.

delete_device() → `None`

Uninitialize the device.

create_component_manager() → `PowerSwitchComponentManager`

Create and return a component manager for this device.

Returns

a component manager for this device

init_command_objects() → `None`

Sets up the command objects.

write_simulationMode(value: `ska_tango_base.control_model.SimulationMode`) → `None`

Set the simulation mode of the device. When simulation mode is set to True, the power switch software simulator is used in place of the hardware. When simulation mode is set to False, the real power switch driver is used.

Parameters

value – `SimulationMode`

read_numOutlets() → `int`

Get the number of outlets.

Returns

number of outlets

read_isCommunicating() → `bool`

Get whether or not the power switch is communicating.

Returns

True if power switch can be contacted, False if not

class `InitCommand(*args: Any, **kwargs: Any)`

Bases: `InitCommand`

A class for the PowerSwitch's `init_device()` "command".

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for device initialisation.

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

class `TurnOnOutletCommand(*args: Any, **kwargs: Any)`

Bases: `ResponseCommand`

The command class for the TurnOnOutlet command.

Turn on an individual outlet, specified by the outlet ID

do(*argin: str*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Implement TurnOnOutlet command functionality.

Parameters

argin – the outlet ID of the outlet to switch on

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

class `TurnOffOutletCommand(*args: Any, **kwargs: Any)`

Bases: `ResponseCommand`

The command class for the TurnOffOutlet command.

Turn off an individual outlet, specified by the outlet ID.

do(*argin: str*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Implement TurnOffOutlet command functionality.

Parameters

argin – the outlet ID of the outlet to switch off

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

class `GetOutletPowerModeCommand(*args: Any, **kwargs: Any)`

Bases: `BaseCommand`

The command class for the GetOutletPowerMode command.

Get the power mode of an individual outlet, specified by the outlet ID.

do(*argin: str*) → `ska_tango_base.control_model.PowerMode`

Implement GetOutletPowerMode command functionality.

Parameters

argin – the outlet ID to get the state of

Returns

power mode of the outlet

6.6.2 PowerSwitchComponentManager Class

class `ska_mid_cbf_mcs.power_switch.power_switch_component_manager.PowerSwitchComponentManager(*args: Any, **kwargs: Any)`

Bases: `CbfComponentManager`

A component manager for the power switch. Calls either the power switch driver or the power switch simulator based on the value of simulation mode.

Parameters

- **simulation_mode** – simulation mode identifies if the real power switch driver or the simulator should be used
- **protocol** – Connection protocol (HTTP or HTTPS) for the power switch
- **ip** – IP address of the power switch
- **login** – Login username of the power switch
- **password** – Login password for the power switch
- **logger** – a logger for this object to use

property num_outlets: `int`

Get number of outlets present in this power switch.

Returns

number of outlets

property is_communicating: `bool`

Returns whether or not the power switch can be communicated with.

Returns

whether the power switch is communicating

property simulation_mode: `ska_tango_base.control_model.SimulationMode`

Get the simulation mode of the component manager.

Returns

simulation mode of the component manager

start_communicating() → `None`

Perform any setup needed for communicating with the power switch.

stop_communicating() → `None`

Stop communication with the component.

get_outlet_power_mode(outlet: `str`) → `ska_tango_base.control_model.PowerMode`

Get the power mode of a specific outlet.

Parameters

outlet – outlet ID

Returns

power mode of the outlet

Raises

`AssertionError` – if outlet ID is out of bounds

turn_on_outlet(outlet: `str`) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Tell the power switch to turn on a specific outlet.

Parameters

outlet – outlet ID to turn on

Returns

a tuple containing a return code and a string message indicating status

Raises

`AssertionError` – if outlet ID is out of bounds

turn_off_outlet(*outlet: str*) → `Tuple[ska_tango_base.commands.ResultCode, str]`

Tell the power switch to turn off a specific outlet.

Parameters

outlet – outlet ID to turn off

Returns

a tuple containing a return code and a string message indicating status

Raises

AssertionError – if outlet ID is out of bounds

get_power_switch_driver(*model: str, ip: str, login: str, password: str, logger: Logger*)

6.6.3 PowerSwitchDriver

```
class ska_mid_cbf_mcs.power_switch.power_switch_driver.PowerSwitchDriver(protocol: str, ip: str,
                                                                           login: str, password:
                                                                           str, content_type: str,
                                                                           outlet_list_url: str,
                                                                           outlet_state_url: str,
                                                                           outlet_control_url:
                                                                           str, turn_on_action:
                                                                           str, turn_off_action:
                                                                           str, state_on: str,
                                                                           state_off: str,
                                                                           outlet_schema_file:
                                                                           str, outlet_id_list:
                                                                           List[str], logger:
                                                                           Logger)
```

Bases: `object`

A driver for the DLI web power switch.

Parameters

- **protocol** – Connection protocol (HTTP or HTTPS) for the power switch
- **ip** – IP address of the power switch
- **login** – Login username of the power switch
- **password** – Login password for the power switch
- **content_type** – The content type in the request header
- **outlet_list_url** – A portion of the URL to get the list of outlets
- **outlet_state_url** – A portion of the URL to get the outlet state
- **outlet_control_url** – A portion of the URL to turn on/off outlet
- **turn_on_action** – value to pass to request to turn on an outlet
- **turn_off_action** – value to pass to request to turn on an outlet
- **state_on** – value of the outlet's state when on
- **state_off** – value of the outlet's state when off
- **outlet_schema_file** – File name for the schema for a list of outlets

- **outlet_id_list** – List of Outlet IDs
- **logger** – a logger for this object to use

query_timeout_s = 6

Timeout in seconds used when waiting for a reply from the power switch

initialize() → `None`

Initializes any variables needed for further communication with the power switch. Should be called once before any of the other methods.

property num_outlets: `int`

Get number of outlets present in this power switch.

Returns

number of outlets

property is_communicating: `bool`

Returns whether or not the power switch can be communicated with.

Returns

whether the power switch is communicating

get_outlet_power_mode(outlet: `str`) → `ska_tango_base.control_model.PowerMode`

Get the power mode of a specific outlet.

Parameters

outlet – outlet ID

Returns

power mode of the outlet

Raises

- **AssertionError** – if outlet ID is out of bounds
- **AssertionError** – if outlet power mode is different than expected

turn_on_outlet(outlet: `str`) → `tuple[ResultCode, str]`

Tell the DLI power switch to turn on a specific outlet.

Parameters

outlet – outlet ID to turn on

Returns

a tuple containing a return code and a string message indicating status

Raises

AssertionError – if outlet ID is out of bounds

turn_off_outlet(outlet: `str`) → `tuple[ResultCode, str]`

Tell the DLI power switch to turn off a specific outlet.

Parameters

outlet – outlet ID to turn off

Returns

a tuple containing a return code and a string message indicating status

Raises

AssertionError – if outlet ID is out of bounds

`get_outlet_list()`

Query the power switch for a list of outlets and get their name and current state.

Returns

list of all the outlets available in this power switch, or an empty list if there was an error

6.6.4 PowerSwitchSimulator

```
class ska_mid_cbf_mcs.power_switch.power_switch_simulator.PowerSwitchSimulator(model: str,
                                                                              logger:
                                                                              Logger)
```

Bases: `object`

A simulator for the power switch.

Parameters

- **model** – Name of the power switch model
- **logger** – a logger for this object to use

property num_outlets: `int`

Get number of outlets present in this power switch.

Returns

number of outlets

property is_communicating: `bool`

Returns whether or not the power switch can be communicated with.

Returns

simulator always returns True

get_outlet_power_mode(outlet: str) → ska_tango_base.control_model.PowerMode

Get the power mode of a specific outlet.

Parameters

outlet – outlet ID

Returns

power mode of the outlet

Raises

AssertionError – if outlet ID is out of bounds

turn_on_outlet(outlet: str) → tuple[ResultCode, str]

Turn on a specific outlet.

Parameters

outlet – outlet ID to turn on

Returns

a tuple containing a return code and a string message indicating status

Raises

AssertionError – if outlet ID is out of bounds

turn_off_outlet(outlet: str) → tuple[ResultCode, str]

Turn off a specific outlet.

Parameters

outlet – outlet ID to turn off

Returns

a tuple containing a return code and a string message indicating status

Raises

AssertionError – if outlet ID is out of bounds

get_outlet_list()

Returns a list of 8 outlets, containing their name and current state. The current state is always set to OFF.

Returns

list of all the outlets available in this power switch

6.7 TalonLRU

6.7.1 TalonLRU Device

class `ska_mid_cbf_mcs.talon_lru.talon_lru_device.TalonLRU(*args: Any, **kwargs: Any)`

Bases: `SKABaseDevice`

TANGO device class for controlling and monitoring a Talon LRU.

always_executed_hook() → `None`

Hook to be executed before any attribute access or command.

delete_device() → `None`

Uninitialize the device.

init_command_objects() → `None`

Sets up the command objects.

read_PDU1PowerMode() → `ska_tango_base.control_model.PowerMode`

Read the power mode of the outlet specified by PDU 1.

Returns

Power mode of PDU 1

read_PDU2PowerMode() → `ska_tango_base.control_model.PowerMode`

Read the power mode of the outlet specified by PDU 2.

Returns

Power mode of PDU 2

create_component_manager() → *TalonLRUComponentManager*

Create and return a component manager for this device.

Returns

a component manager for this device.

class `InitCommand(*args: Any, **kwargs: Any)`

Bases: `InitCommand`

A class for the TalonLRU's `init_device()` “command”.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Stateless hook for device initialisation. Creates the device proxies to the power switch devices.

Returns

A Tuple containing a return code and a string message indicating status. The message is for information purpose only.

class OnCommand(*args: *Any*, **kwargs: *Any*)

Bases: `OnCommand`

The command class for the On command.

Turn on both outlets that provide power to the LRU. Device is put into ON state if at least one outlet was successfully turned on.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Implement On command functionality.

Returns

A Tuple containing a return code and a string message indicating status. The message is for information purpose only.

class OffCommand(*args: *Any*, **kwargs: *Any*)

Bases: `OffCommand`

The command class for the Off command.

Turn off both outlets that provide power to the LRU. Device is put in the OFF state if both outlets were successfully turned off.

do() → `Tuple[ska_tango_base.commands.ResultCode, str]`

Implement Off command functionality.

Returns

A Tuple containing a return code and a string message indicating status. The message is for information purpose only.

6.7.2 TalonLRUComponentManager Class

class `ska_mid_cbf_mcs.talon_lru.talon_lru_component_manager.TalonLRUComponentManager`(*args: *Any*, **kwargs: *Any*)

Bases: `CbfComponentManager`

A component manager for the TalonLRU device.

start_communicating() → `None`

Establish communication with the component, then start monitoring.

stop_communicating() → `None`

Stop communication with the component.

get_device_proxy(fqdn: *str*) → `CbfDeviceProxy | None`

Attempt to get a device proxy of the specified device.

Parameters

fqdn – FQDN of the device to connect to

Returns

`CbfDeviceProxy` to the device or `None` if no connection was made

check_power_mode(*state: tango.DevState*) → *None*

Get the power mode of both PDUs and check that it is consistent with the current device state.

Parameters

state – device operational state

on(*simulation_mode: ska_tango_base.control_model.SimulationMode*) →

Tuple[*ska_tango_base.commands.ResultCode*, *str*]

Turn on the TalonLRU and its subordinate devices

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(*ResultCode*, *str*)

off() → *Tuple*[*ska_tango_base.commands.ResultCode*, *str*]

Turn off the TalonLRU and its subordinate devices

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(*ResultCode*, *str*)

standby() → *Tuple*[*ska_tango_base.commands.ResultCode*, *str*]

Turn the TalonLRU into low power standby mode

Returns

A tuple containing a return code and a string message indicating status. The message is for information purpose only.

Return type

(*ResultCode*, *str*)

6.8 TalonDxLogConsumer

6.8.1 TalonDxLogConsumer Class

```
class ska_mid_cbf_mcs.talondx_log_consumer.talondx_log_consumer_device.TalonDxLogConsumer(*args:
Any,
**kwargs:
Any)
```

Bases: SKABaseDevice

TANGO device class for consuming logs from the Tango devices run on the Talon boards, converting them to the SKA format, and outputting them via the logging framework.

create_component_manager()

Create the component manager LogComponentManager

Returns

Instance of LogComponentManager

Return type

LogComponentManager

Log(*log_message*: *List[str]*)

Write the log to stdout as received from TLS

Sample log: ['1650964795495', 'ERROR', 'ska001/elt/master', 'TangoUtils::DeviceAttributeToCorbaAny() - A Message', '@7f48dcc80700 [7]']

Details of the list items here: <https://tango-controls.readthedocs.io/projects/rfc/en/latest/14/Logging.html#log-consumer>

Parameters

log_message (*List[str]*) – Parts of the TLS log message

SetTalonDxLogConsumerTarget(*device_name*: *str*) → *None*

Add TalonDxLogConsumer as a logging target destination on device

RemoveTalonDxLogConsumerTarget(*device_name*: *str*) → *None*

Remove TalonDxLogConsumer as a logging target destination on device

write_loggingLevel(*value*: *ska_tango_base.control_model.LoggingLevel*)

Sets logging level for the device. Both the Python logger and the Tango logger are updated. Overrides the base class attribute to accept all log levels coming from HPS devices, but still limit the logging level of TalonDxLogConsumer logs.

Parameters

value – Logging level for logger

Raises

LoggingLevelError – for invalid value

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